

GOVP1199801719

635.987
L293L
V.2

최	종
연구보고서	

**농가보급형 무인 양액관리 시스템
및 활용기술 개발에 관한 연구**

**Development of an Unmanned Nutrient-Solution
Control System and its Application Technology**

연구기관

서울대학교

농림부

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1997. 12. 29.

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SUMMARY

This study was conducted to develop an automatic nutrient-solution control system and its application technology. Temperature, electronic conductivity(EC), and pH were selected as control variables. The nutrient-solution mixing system consisted of a low-cost and precise metering device, A/DC and microcomputer with a F8680A. The overflow type metering device was composed of three parts those were supply pumps, metering cylinders and venturi tube. The usefulness of overflow type metering device was certified by regression between A and B device and comparing the amount of discharge. Nutrient-solution system uses metering device instead of high price metering pumps.

The system controlled electric conductivity(EC) and pH of nutrient-solution based on the fuzzy logic controller by fuzzy control algorithm in control and supply routine. Fuzzy controller was certified by simulation and experiment. Also an experimental cultivation of tomato was conducted to verify and to improve the developed system.

The major results of the study are summarized as follows.

1. By Measuring of the nutrient-solution state sensors were selected. Selected sensors were temperature sensor, electronic conductivity sensor, pH sensor and environmental sensor which were solar radiation sensor, temperature and humidity sensor.
2. Low-cost and precise metering device which reduced supply error

between A and B liquid was developed. And controller which determine supply amount and control actuator was developed.

3. A low-cost and precise overflow type metering device was developed for the automatic nutrient-solution mixing system for small hydroponic growers. The accuracy of the overflow type metering device in terms of the FS error was 0.2% by using solenoid valve and flow control valve together. But two type commercial pump was $\pm 2.45\%$ and $\pm 1.38\%$ FS error respectively.

4. The developed nutrient-solution control system showed ± 0.05 mS/cm of deviation from the setting EC value over the experimental cultivation period. And the deviation from the average values of Ca and Mg mass content in the several nutrient-solution were 0.5% and 1.8% respectively.

5. By developing a controller considering EC, pH and environmental factors, It was possible to use fuzzy prediction algorithm in nutrient-solution system. Fuzzy Inference makes us prediction of EC and supply amount with better rule-base. and This information can be used to the automatic nutrient-solution mixing system.

6. Fuzzy Inference makes us control EC. and showed a satisfactory control performance with the max overshooting of 0.035mS/cm and max settling time of 15minute within 0.7mS/cm EC error range.

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5.	83
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7.	83
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가.	100
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.	101
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4.	105
5	106
1.	106
가.	106
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2.	111
가.	111
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.	113
.	115
3.	116
가.	116
1)	116
2)	117
.	119
6	122
6	123
	128

1

1

,
가
가
가
1954
167.7ha 42 가
10
가
가
가
가
가
(C), (O), (H), (P), (K) 가 16

가

가 (CO2)

, ,

가
가

,
가
가 가

,
가
가

가

2

1.

가 ,
가 ,
가 ,
가 ,
RotaDos
6000 가
가
가

EC pH

가

()

4가 가

1500 가 , , ,

200 가

NETAFIM 60 3가

가 6000

Blue White

가 , 2000

100%

Total package

2.

가

流路

가

가

가

가

가

가

3

1.

가.

가

2.

가.

가

ON-OFF

가

가 가

.

, ,

가

.

4

.

1.

2.

3.

가
가

2

1

MC68705

2

가 , ,

, 가

가

3

1.

A, B

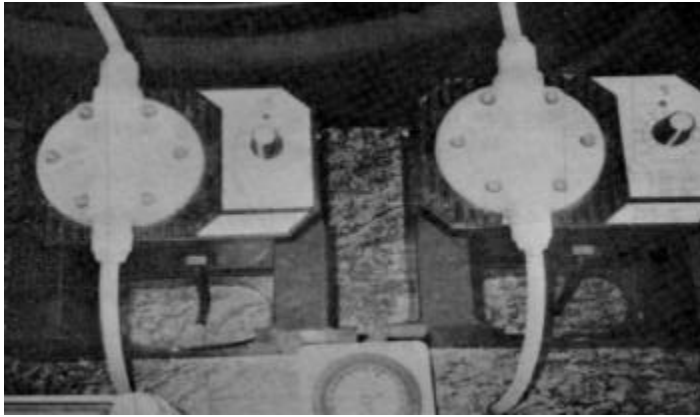
100 1000

< 2-1>

< 2-1>

< 2-1>

	HANNA (Italy)	110VAC	200W	5l/h
A, B	HANNA (Italy)	220VAC	200W	15l/h

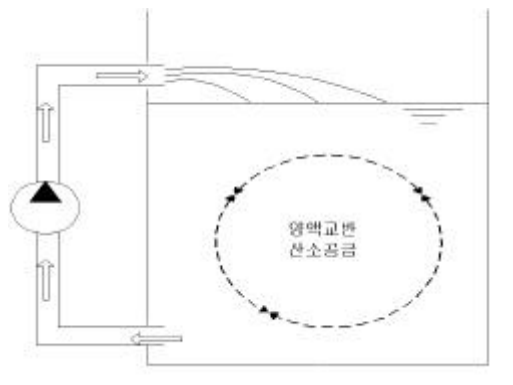


< 2-1 >

2.

가

< 2-2 >



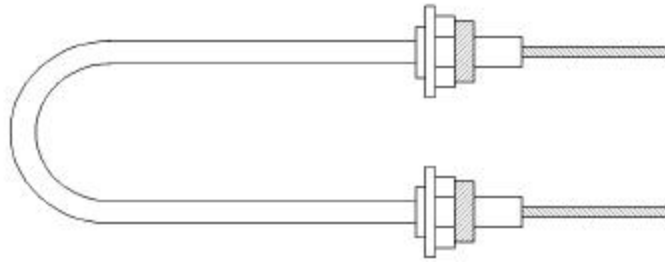
< 2-2 >

3.

(batch) 1
 가 .
 1 , , , 1
 < 2-1> .
 = $\frac{\times \times}{\text{가}}$ < 2-1>
 300 ,
 600 가 ,
 1000

4.

가 < 2-2>
 = $\frac{\times \times}{\text{가}}$ < 2-2>
 17 , 1000 , 20 , 가
 10 21kW 가 . <
 2-3> .



< 2-3 >

5.

6.

A, B

4

1.

가

가

,
가 가
가

ON/OFF

가 (dead band)

0.1 가

2.

MOTOROLA MC68705 32 가

, 4 A/D . < 2-2> MC68705

PCB < 2-4>

, < 2-5> , < 2-6> PCB

4 7 LED

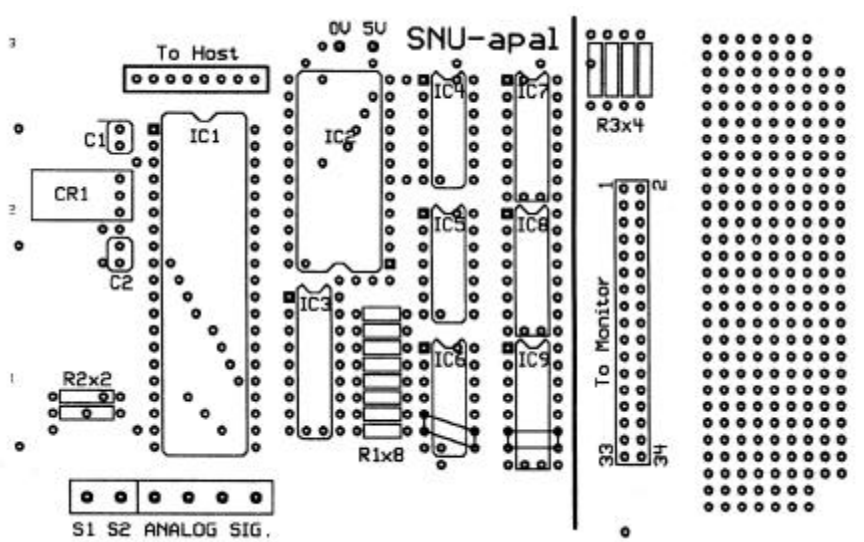
가, 4

4 LED . < 2-7>

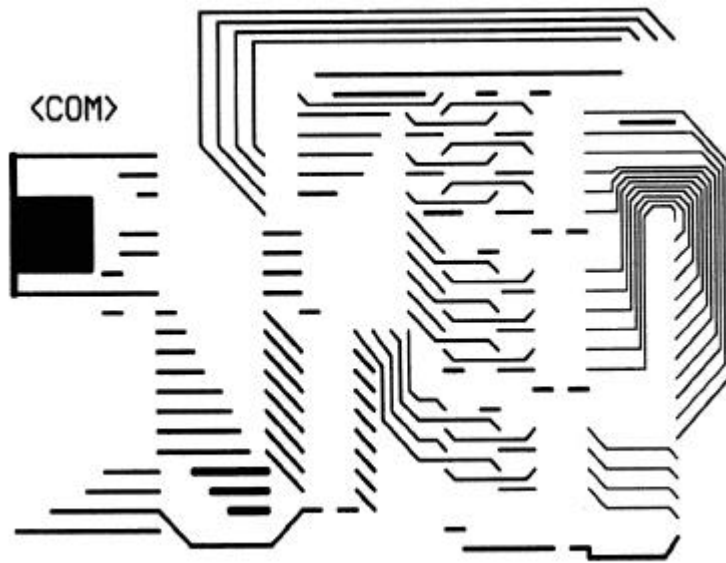
< 2-8>

< 2-2> MC68705

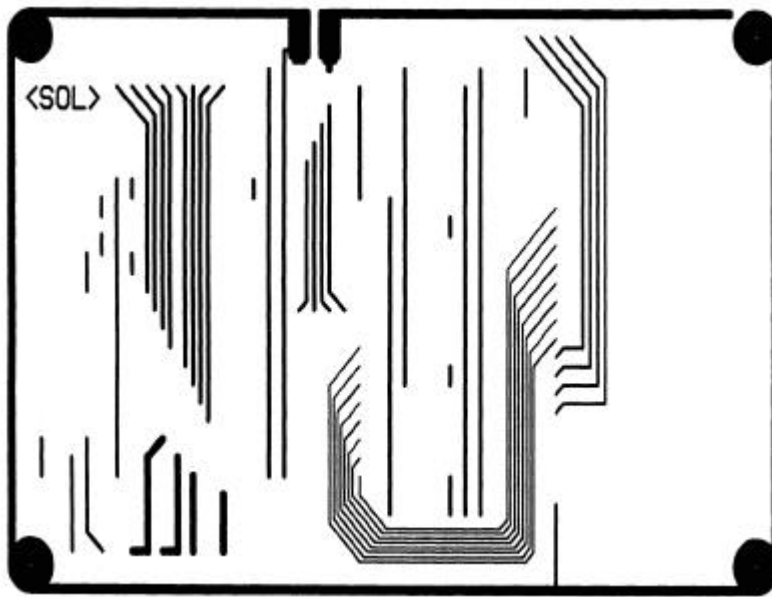
Manufacturer	MOTOROLA (USA)
Model	MC68705R3
RAM	112 bytes
ROM	3968 bytes
Digital I/O port	Port A, B, C(bidirectional) Port D(input)
Analog Input	4 channel, 8 bit A/D conversion
external clock	4Mhz



< 2-4>



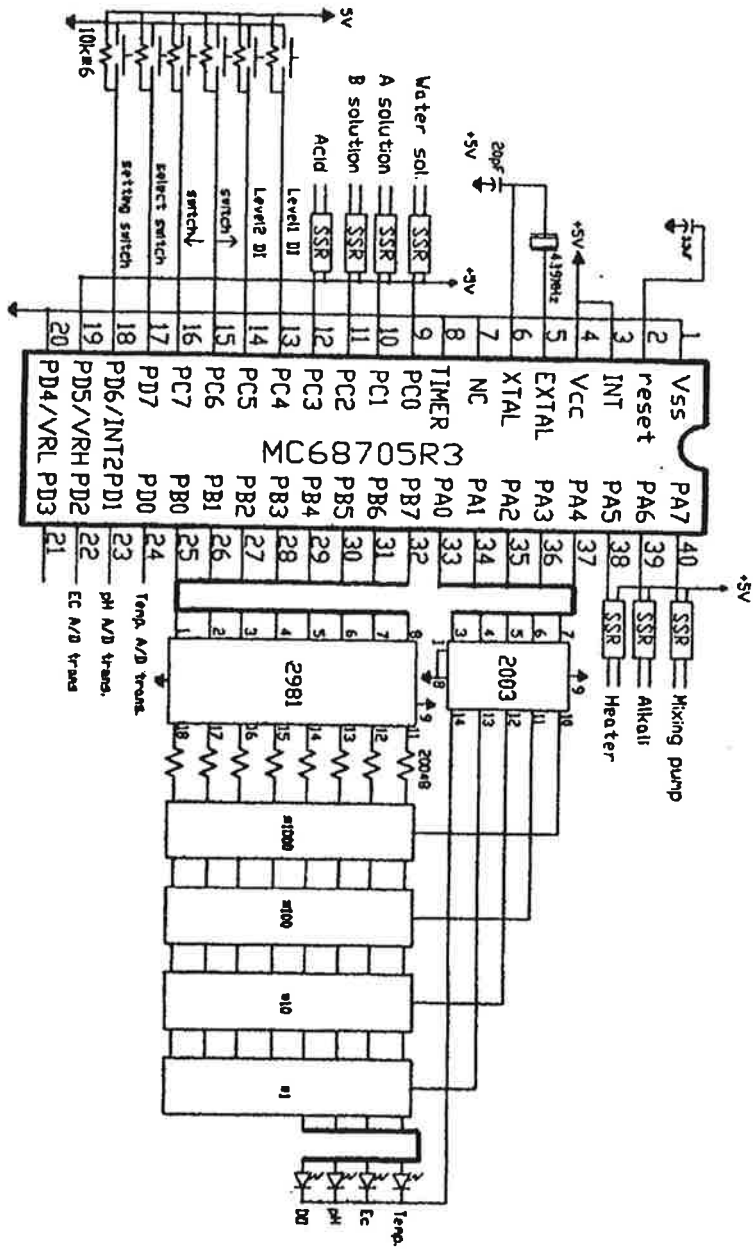
< 2-5 >



< 2-6 >



< 2-7 >



<그림 2-8> 제어기 회로도

3.

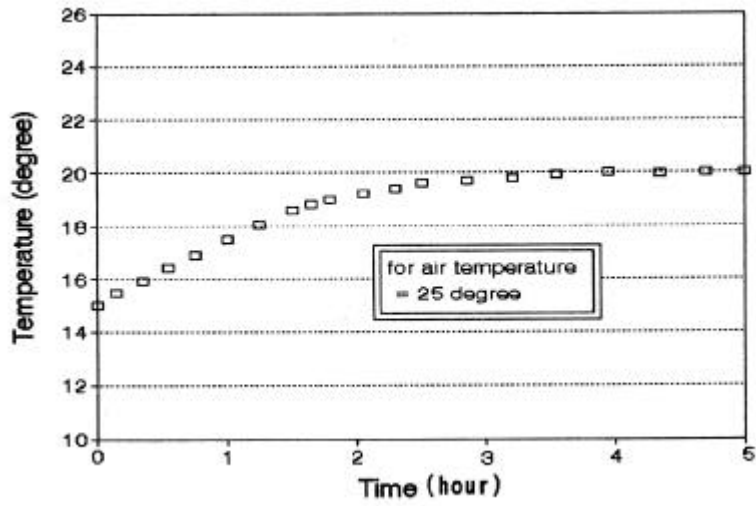
가.

< 2-9 >

15

5

2, 0.06



< 2-9 >

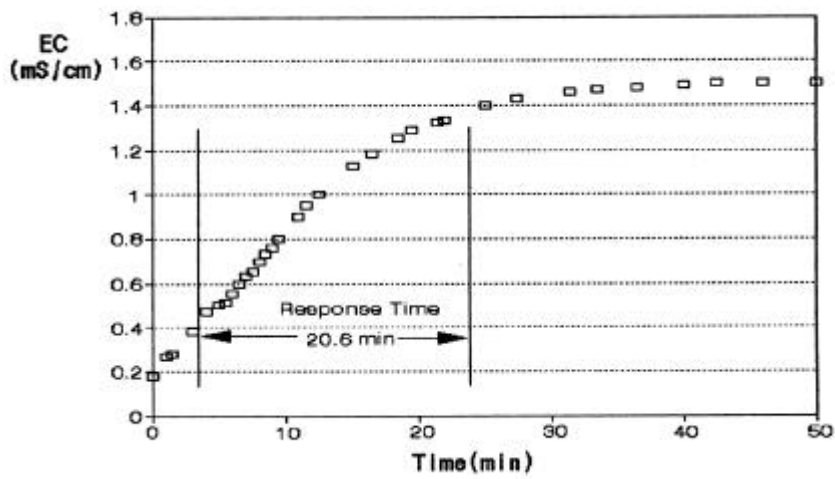
< 2-10 >

50

1.5mS/cm

20 6

0.03mS/cm



< 2-10>

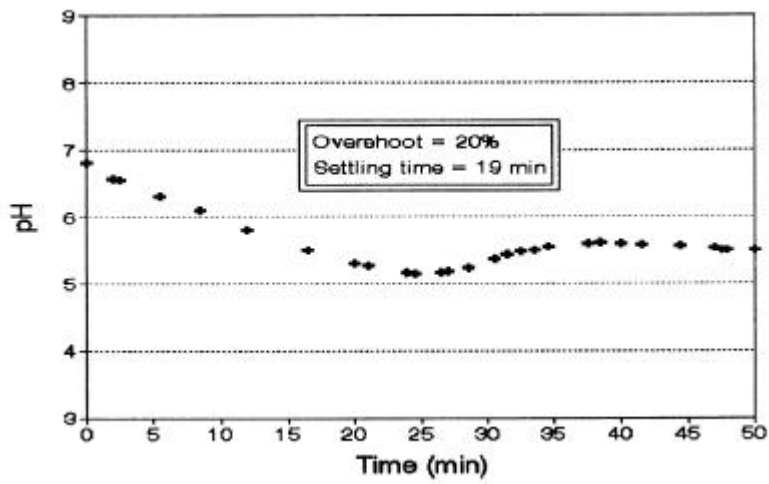
(H₂SO₄),

(NaOH) 0.1M

< 2-11>

19 ,

0.08pH



< 2-11>

5

300

20

가

가

2-3>

< 2-3>

	2.2 mS/cm	± 0.3 mS/cm
	6.0 pH	± 0.2 pH
	17	± 2

6

가 가 가

3.

3. 1.

가 가 , 가
가
가 가 ,
가 가 .

3. 2.

가 , 가
(diaphragm)
가
가
가 가

-
- 가

3. 3.

(float type)

3. 4.

3.4.1.

- 3.4.1.1. 가 가 가 .
- 3.4.1.2. .
- 3.4.1.3. .
- 3.4.1.4. 100 가 .

3.4.2.

3.4.2.1.

가 .

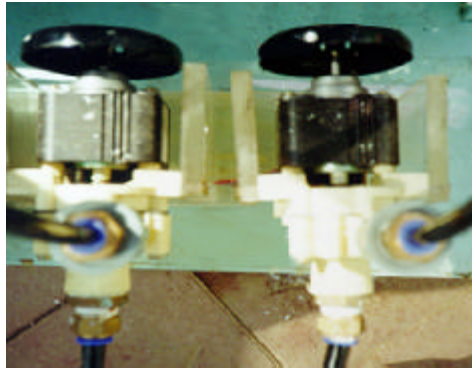
. <

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< 3- 1>

< 3-1>

	200 × 100 × 150 mm
	3kg
	110/220V; 50/60Hz



< 3-1 >

3.4.2.2.

가

가

가

< 3-1 > < 3-2 >

$$Q = \frac{A \times V}{1000} = \left(\frac{\pi D^2}{4} \right) \times \frac{V}{1000} \quad < 3-1 >$$

$$V = \sqrt{2gH} \quad < 3-2 >$$

Q = (/s),
A = (cm²),
V = (cm/s),
D = (cm),
H = (cm),
g = 가 (cm/s²).

20 cm, 10 %

9.53 mm (3/8 in) < 3-2>

< 3-2>

Contents	Specifications
Type	Cylinder (80 × H30 mm)
Height	20 mm
Diameter	9.53 mm (3/8 in)
Material	Acryl

(float type)

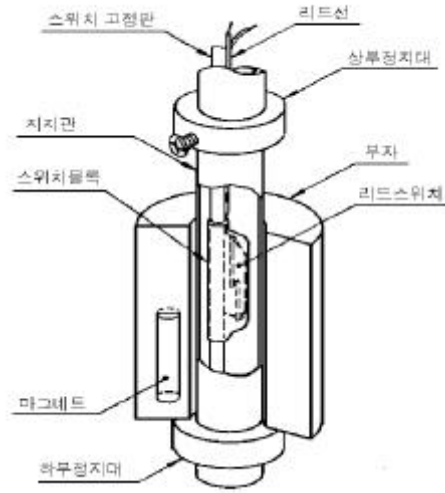
(magnetic float)

(reed switch)

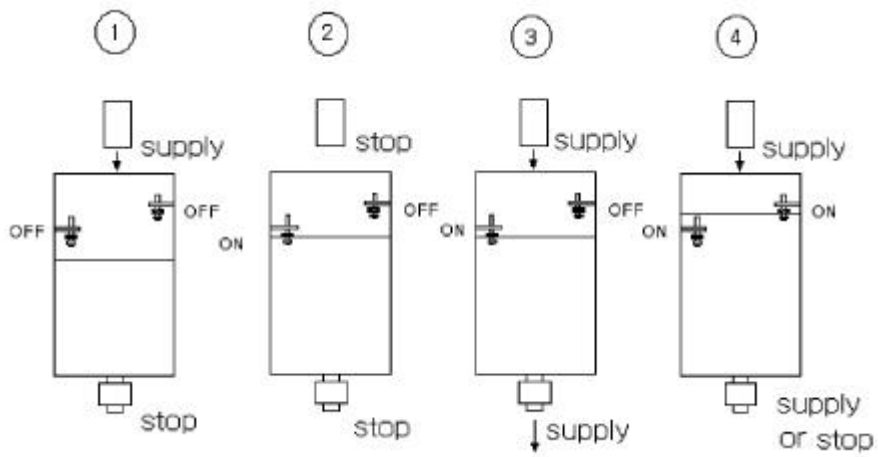
(reed switch)

가 . < 3-2>

< 3-3>



< 3-2>



< 3-3>

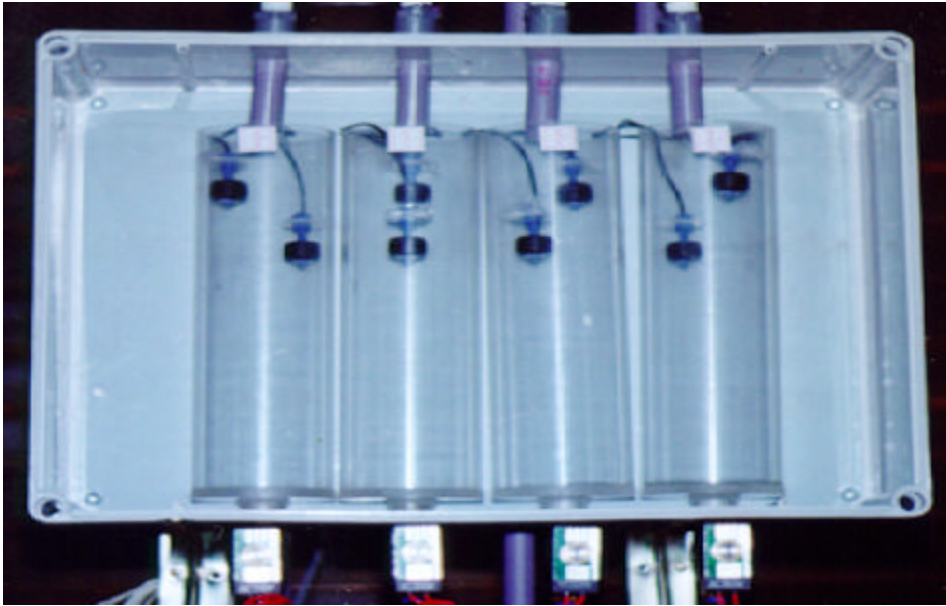
가

. < 3-3>

< 3-4>

< 3-3>

Manufacturer	Diameter (in)	Orifice (mm)	Area (mm ²)	Pressure min. (MPa)	Pressure max. (MPa)	Weight (g)	Power
SMC	3/8	10	43	0.05	2	550	220 V; 60 Hz



< 3-4 >

3.4.2.3.

가

. . < 3-5 >

1 2

< 3-3 >

$$\frac{P_1}{\rho_g} + \frac{V_1^2}{2} + Z_1 = \frac{P_2}{\rho_g} + \frac{V_2^2}{2} + Z_2 \quad < 3-3 >$$

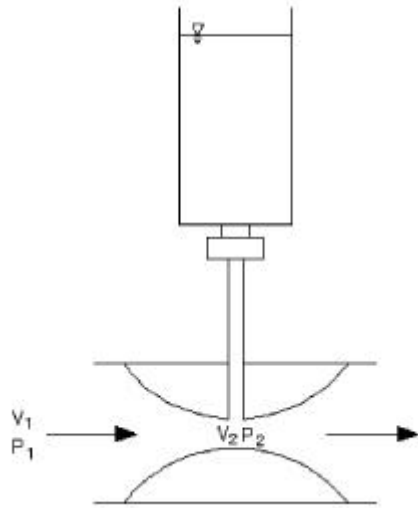
,

$$P_1, P_2 = \quad 1, 2 \quad ,$$

$$V_1, V_2 = \quad 1, 2 \quad ,$$

$$Z_1, Z_2 = \quad 1, 2 \quad ,$$

= .



< 3-5>

< 3-4>

$$Q = A_1 V_1 = A_2 V_2 \quad < 3-4>$$

,

$$Q = \quad ,$$

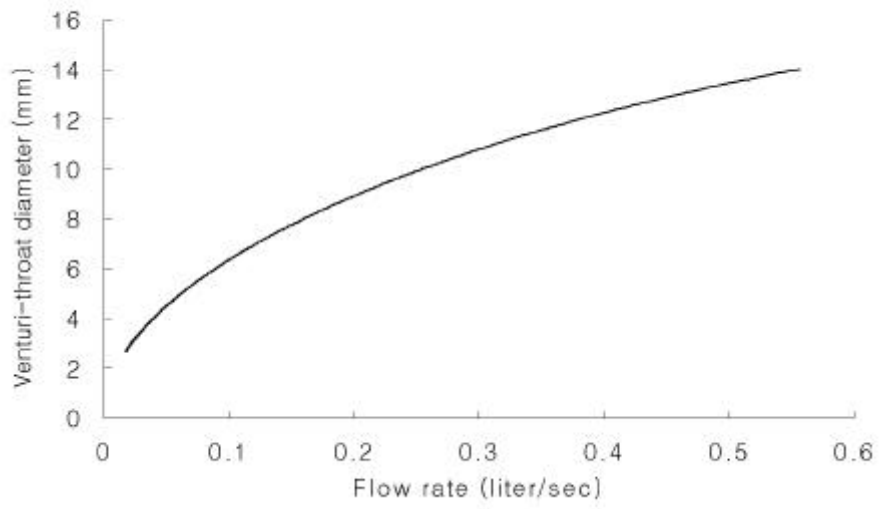
$$A_1, A_2 = \quad 1, 2 \quad .$$

< 3-3> < 3-4> 2

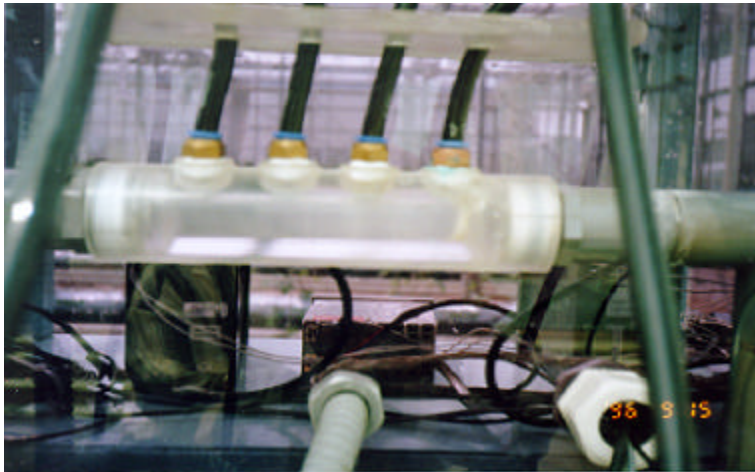
< 3-6>

< 3-7>

2 14 mm .



< 3-6> Relationship between venturi-throat diameter and flow rate.



< 3-7>

3.4.2.4.

3.4.2.5.

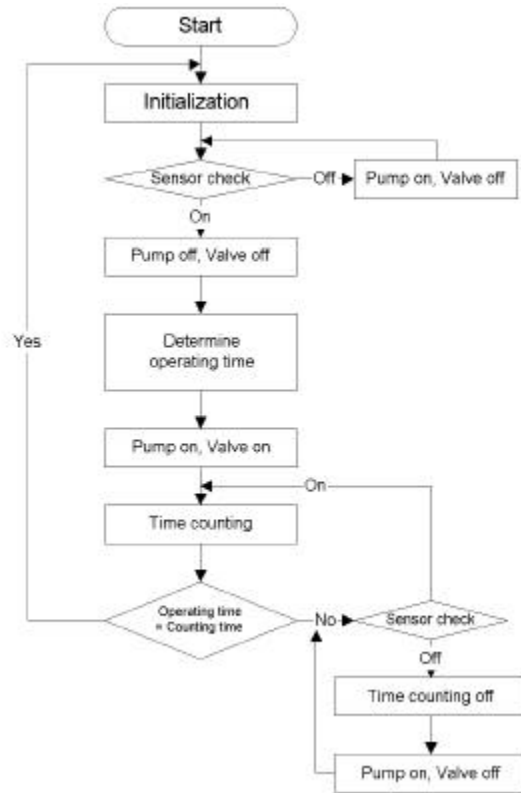
C/C++

DIO

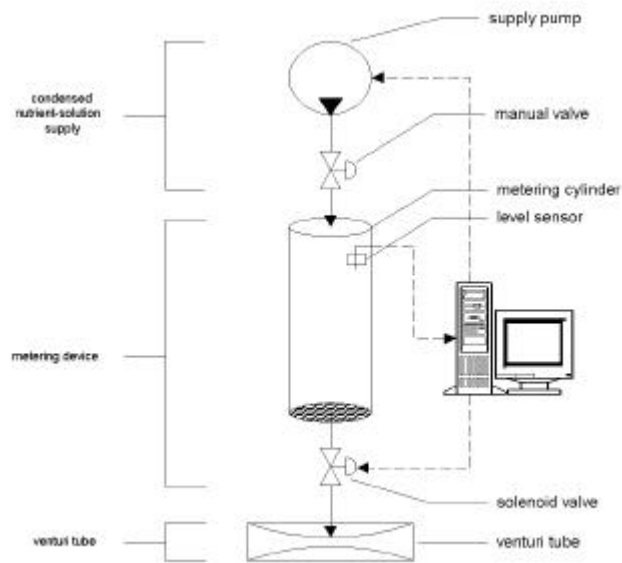
가

. < 3-8>

< 3-9>



< 3-8>



< 3-9>

3. 4. 2. 6.

3. 4. 2. 6. 1. 가

가

가

가

20 cm

10 가 가

4

10

30

4

600

(HANNA, Italy)

(Blue White, USA)

2

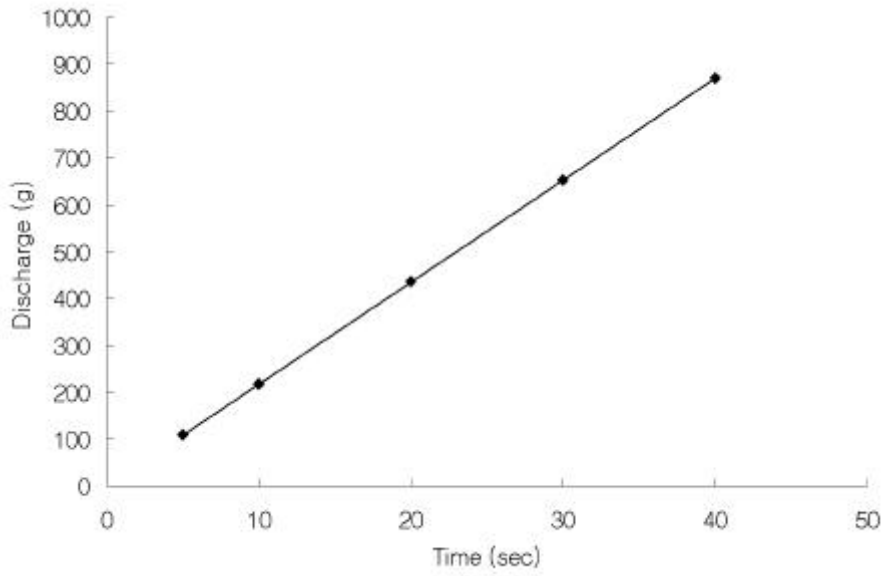
5

30

3. 4. 2. 6. 2.

< 3-10>

< 3-5>



< 3-10>

$$Discharge(g) = 21.759 \times Time(sec) \quad < 3-5>$$

(R²) 0.9999

가 가 .

3. 4. 2. 6. 3.

4

< 3-11> . (HANNA, Italy)

(Blue White, USA) <

3-12> < 3-13> .

4 600

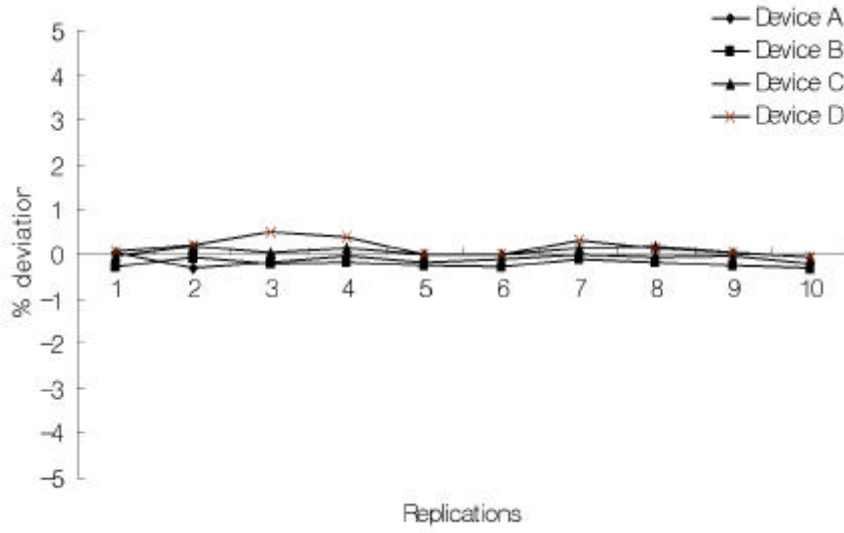
10 30 <

3-11> 가 0.48 % .

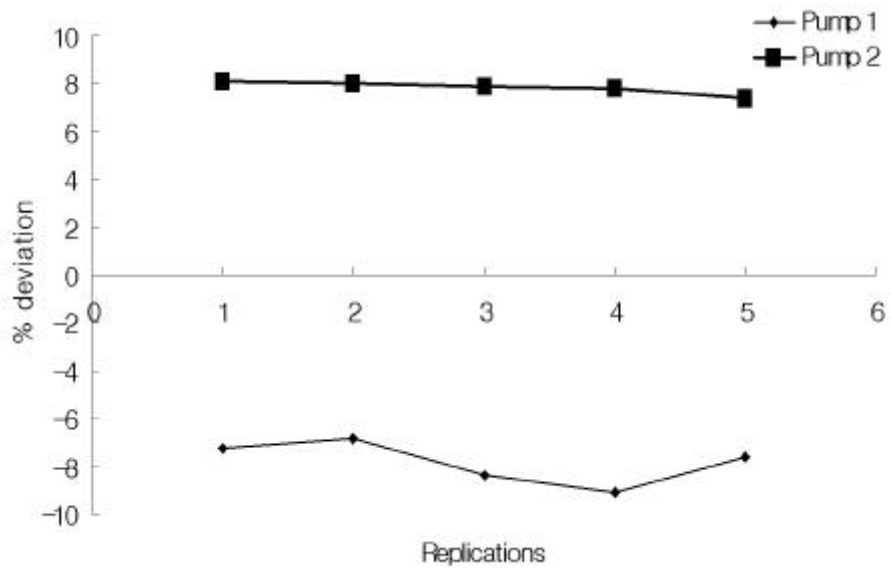
< 3- 12> HANNA 9.11 % , < 3- 13>

Blue White 8.46 % .

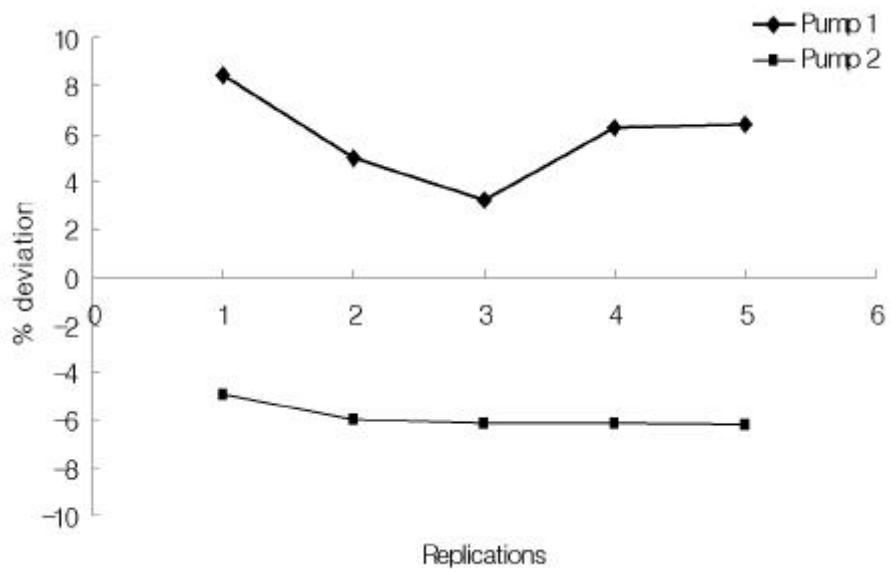
가 가



< 3- 11>



< 3-12> HANNA



< 3-13> Blue White

3.4.3.

3.4.3.1.

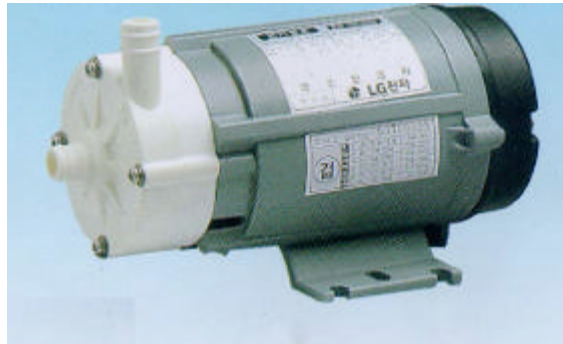
가
가
(bypass)
가

3.4.3.2.

< 3-4> < 3-14>

< 3-4>

Manufacturer	Source	Max flow rate (l/min)	Max head(m)	Operating Temperature
LG(KOREA)	AC 220V 60Hz	19	3.5	60



< 3-14>

3.4.3.3.

①

A, B

⑤

(Q > Q)

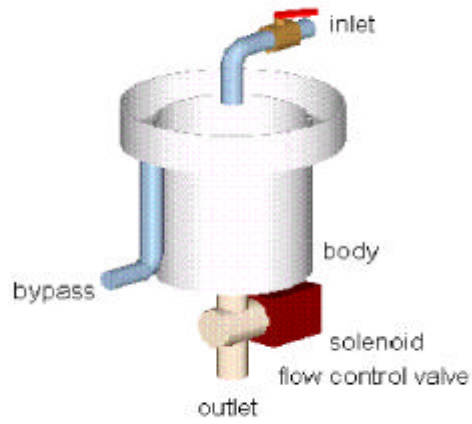
③

④

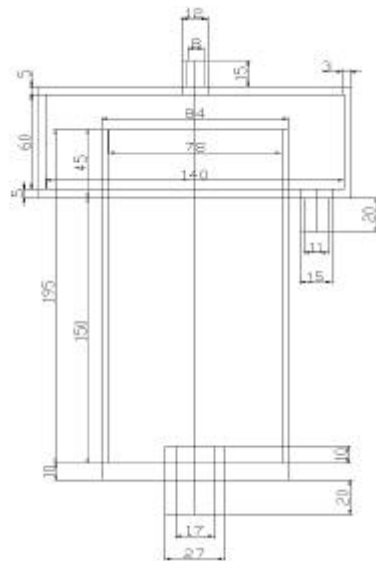
(Q = 0 @ t =)

< 3-15>, <

3-16> < 3-5> .



< 3-15>



< 3-16>

< 3-5>

Material	Diameter(mm)			Height(mm)	Volume(l)
	Inlet	Solenoid orifice	Bypass		
acryl	4	4	11	195	1

3.4.3.4.

4.2pH A 7.8pH B SS(stainless steel)

< 3-6>

< 3-7>

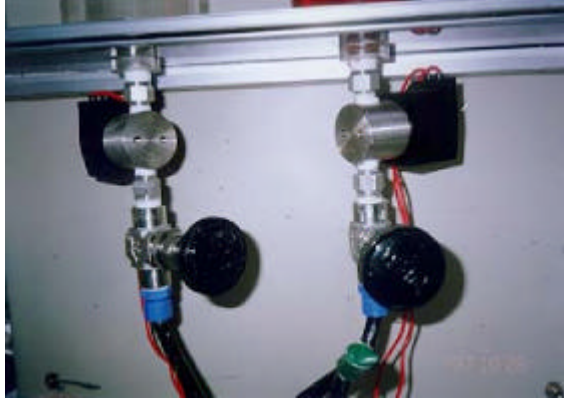
< 3-17>

< 3-6>

Material	Orifice diameter (mm)	Source	Manufacturer
Stainless steel	4	220V 60Hz	CKD (Japan)

< 3-7>

Material	Inner diameter (mm)	Flow coefficient (Cv)	Manufacturer
Stainless steel	6	0.73	Union Metal (Korea)



< 3-17 >

3.4.3.5.

C/C++

DIO

A, B

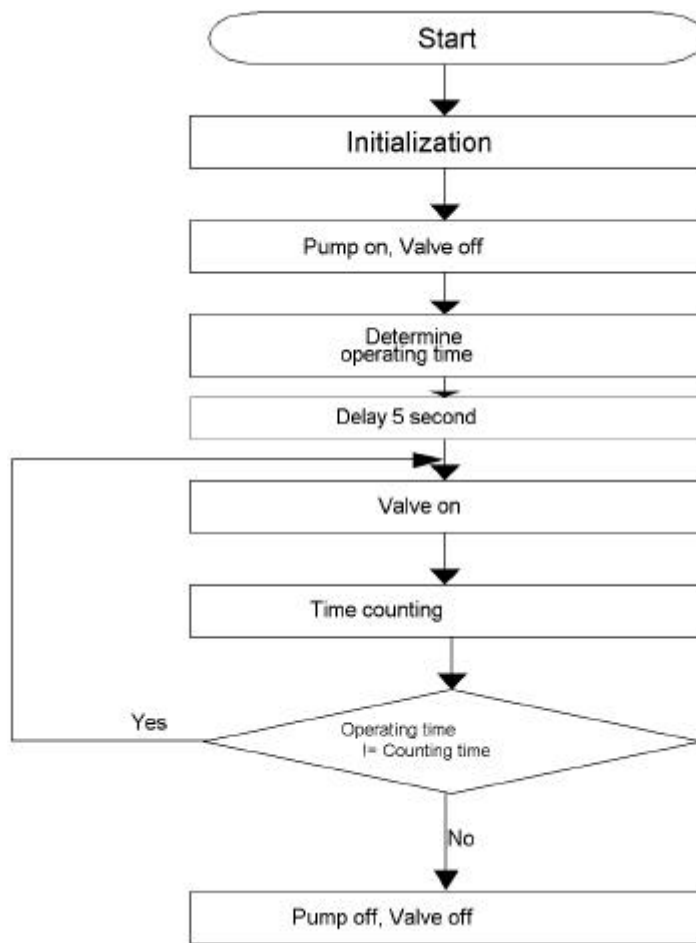
가 , 가

· , A,

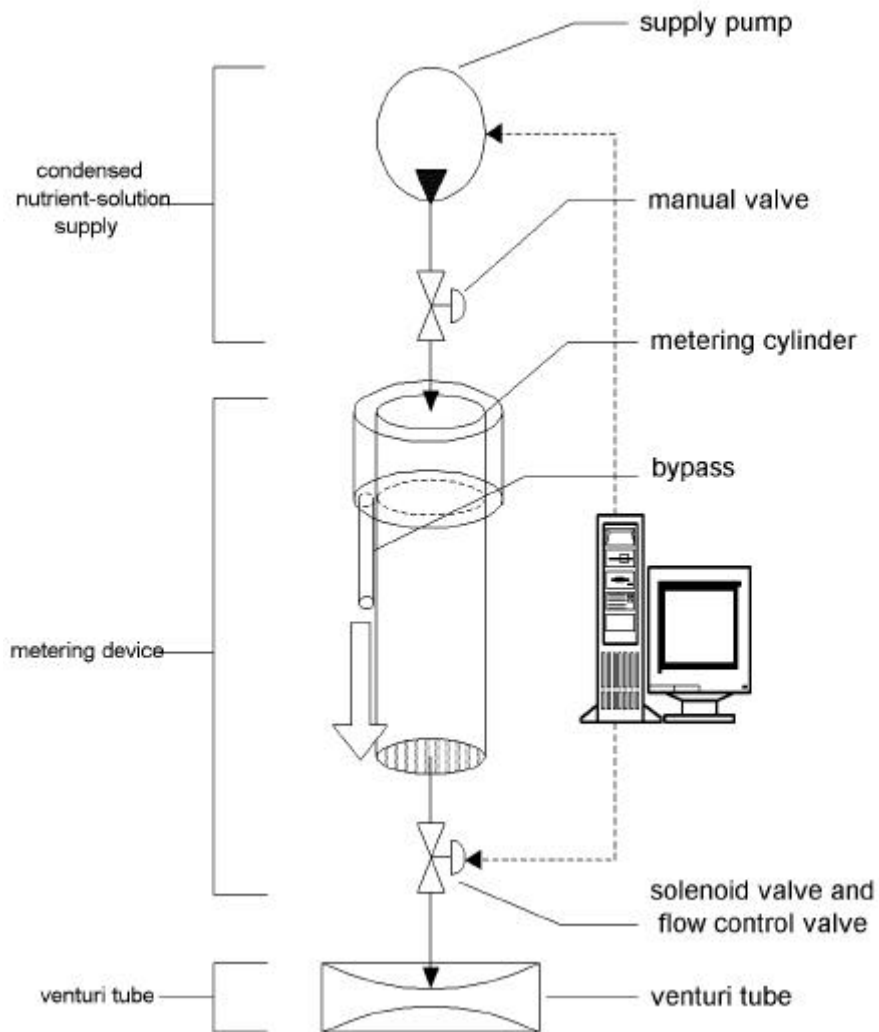
B 가

< 3- 18>

< 3- 19>



< 3- 18>



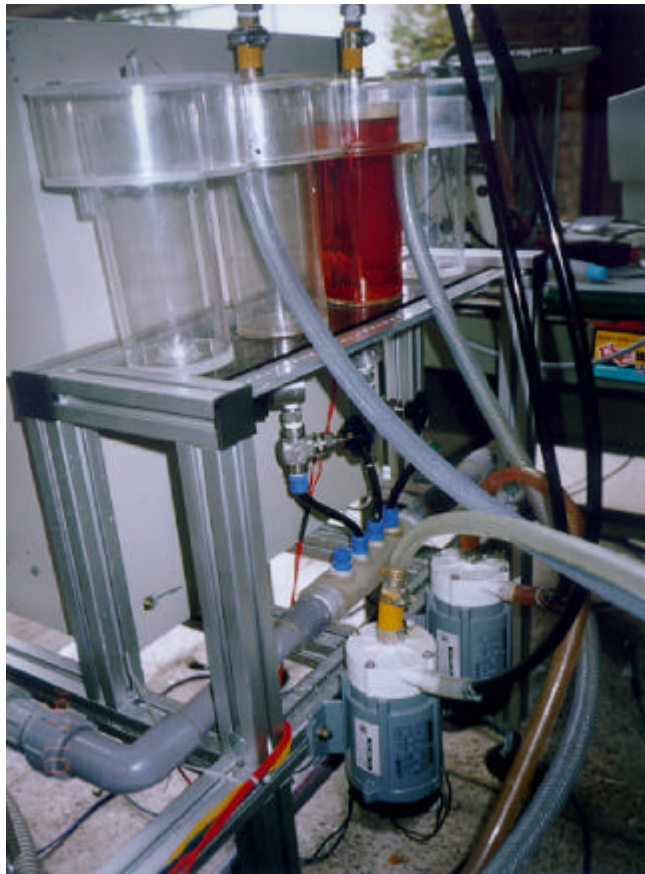
< 3-19>

< 3-20>

, < 3-21>

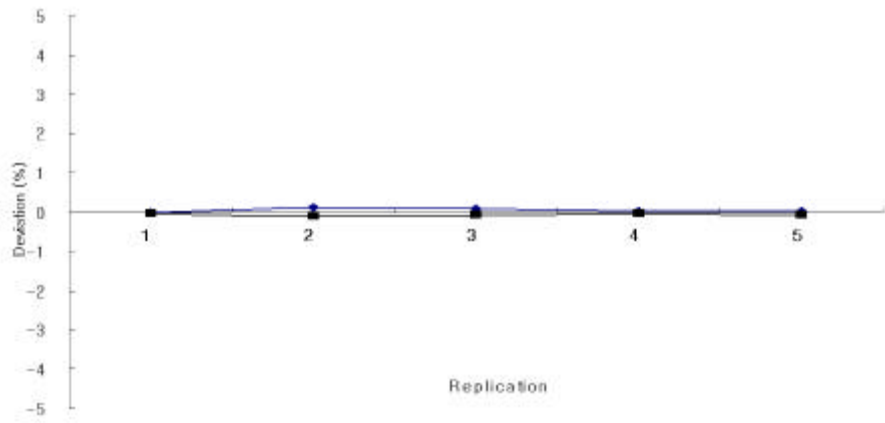


< 3-20>

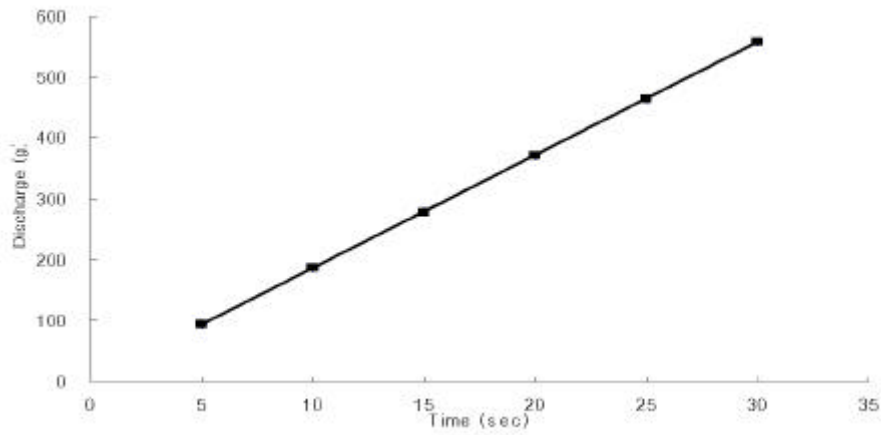


< 3-21>

가 0.2%



< 3- 23>



< 3- 24>

, < 3- 24> ,

< 3- 6>

(R2) 0.999999

가 가

$$Discharge(g) = 18.59 \times Time(sec) \quad < 3- 6>$$

3. 5.

가

가

< 3-8>

, , , .

< 3-8>

	HANNA (Italy)	Blue White (USA)		
		가		가
	9.11%	8.46%	0.48%	0.2%
	, , , 11		4	5

4.

4. 1.

PC

가

가 1 10

4. 2.

4.2.1.

PC

A/D input/output board AXIOM AX5411 12

16 A/D converter 24 DIO 가 . <

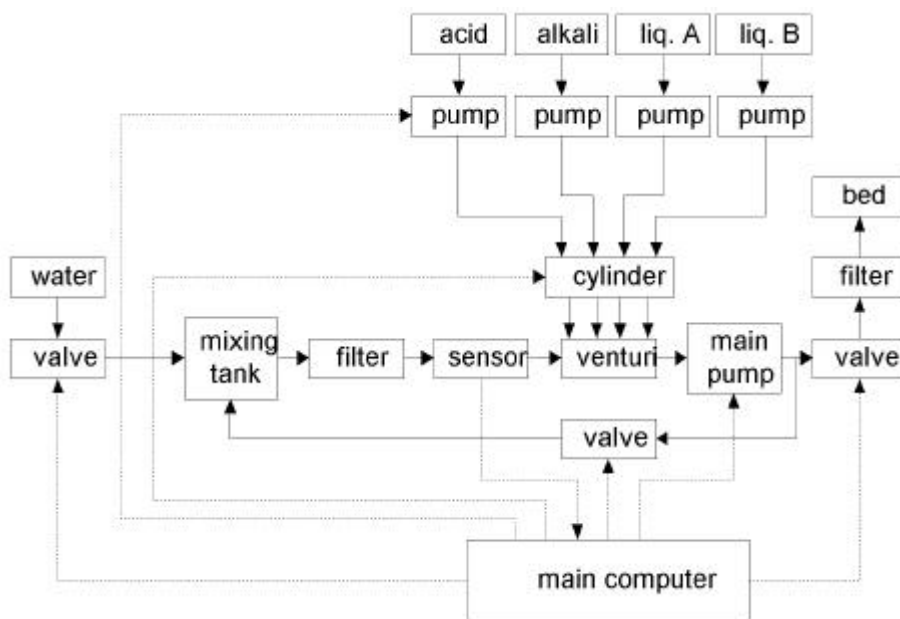
4- 1> AX5411 < 4- 1> PC

< 4- 2>

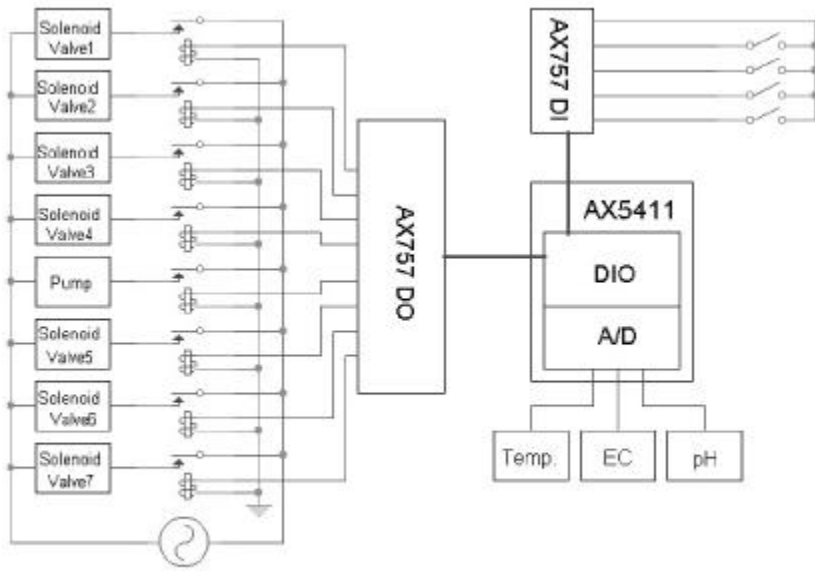
< 4-1>

AX5411

Contents	Specification
Manufacturer	AXIOM
Model	AX5411
A/D	12 bit, 16 channel, 60kHz
D/A	0 5, 5 10V output, 2channel
DIO	24 channel, TTL/DTL compatible
CLOCK	4MHz



< 4-1> PC



< 4-2 >

4.2.2.

< 4-3 >

, Borland

C/C++

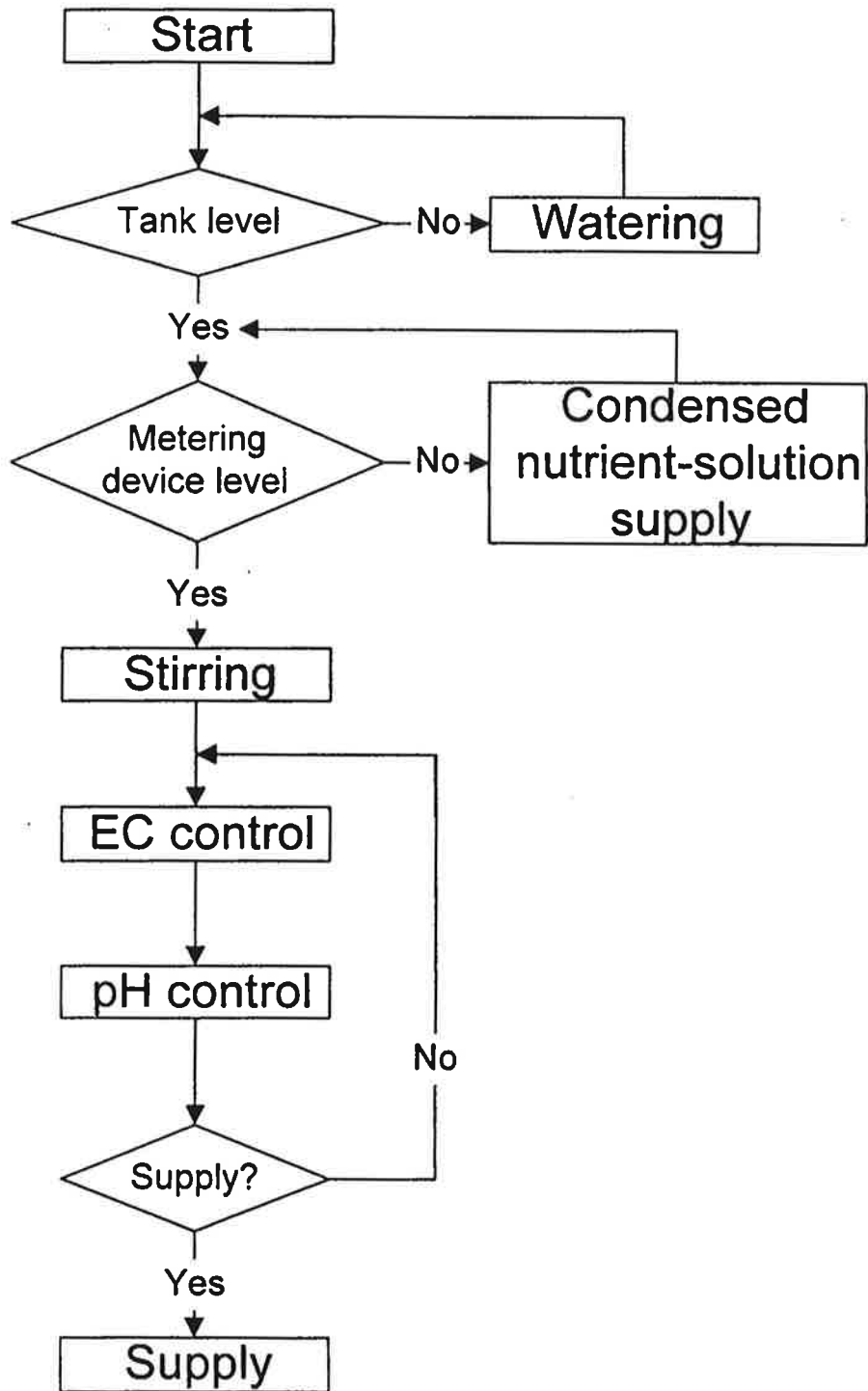
0.1 9.9 mS/cm 가

± 0.05 mS/cm

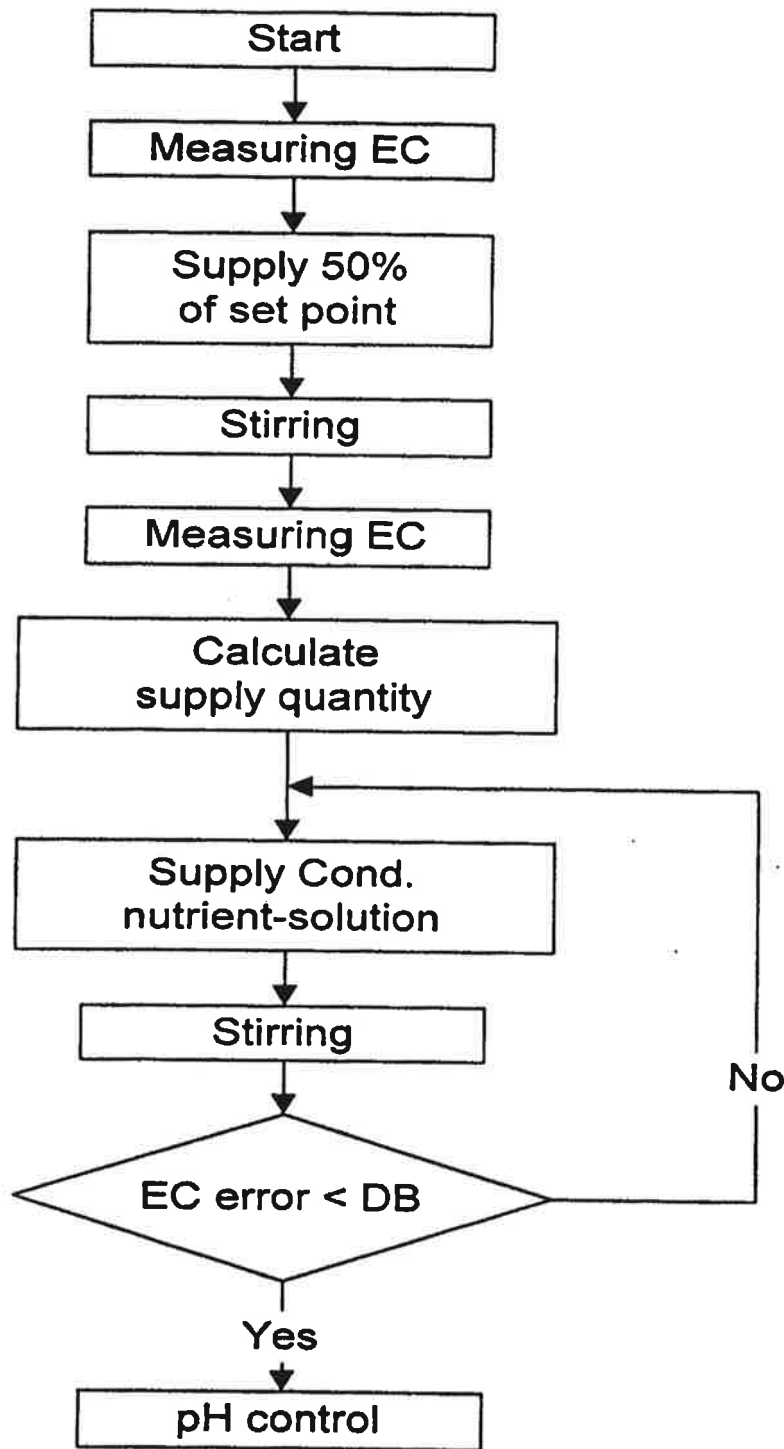
50%

가 가 (feedback)

< 4-4 >



<그림 4-3> 양액 자동 조절 공급 프로그램의 순서도

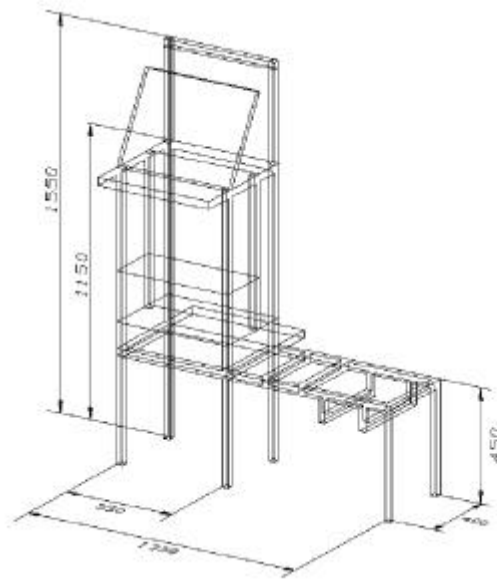


<그림 4-4> 제어 프로그램의 순서도

4.3.

4.3.1.

< 4-5>

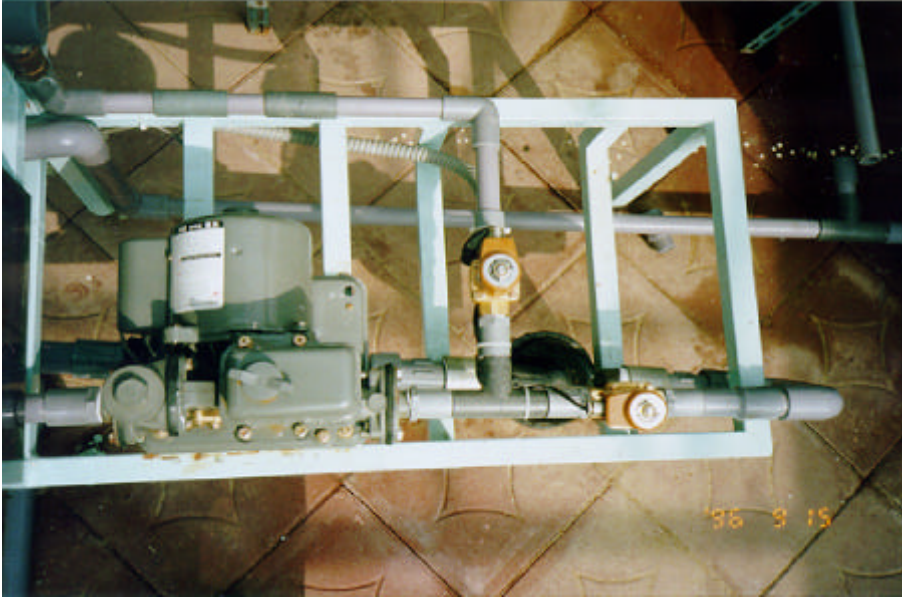


< 4-5>

4.3.2.

< 4-6>

< 4-7>



< 4-6 >



< 4-7 >

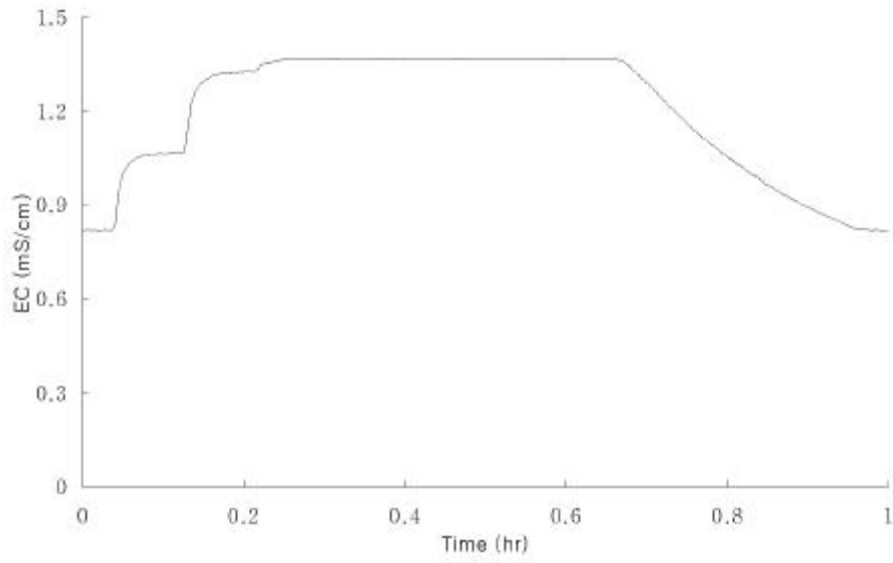
4.3.3.

4.3.3.1.

가

< 4-8 >

24 ± 0.05 mS/cm, 0.8
mS/cm 1.4 mS/cm (settling time) 15



< 4-8 >

NETAFIM

<4-9>

1 50

2 50

가 22

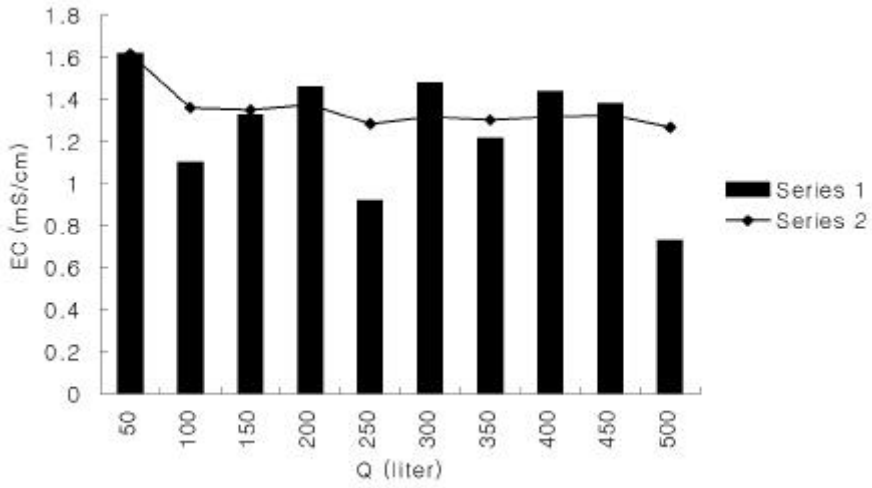
1.4 mS/cm 500

1.29 mS/cm

가

가

가



< 4-9> NETAFIM

4.3.3.2.

가

< 4-10>

24 ±0.2 pH

, 6.4 pH 6.0 pH

(settling time) 15

NETAFIM

< 4-11>

1 50

2 50

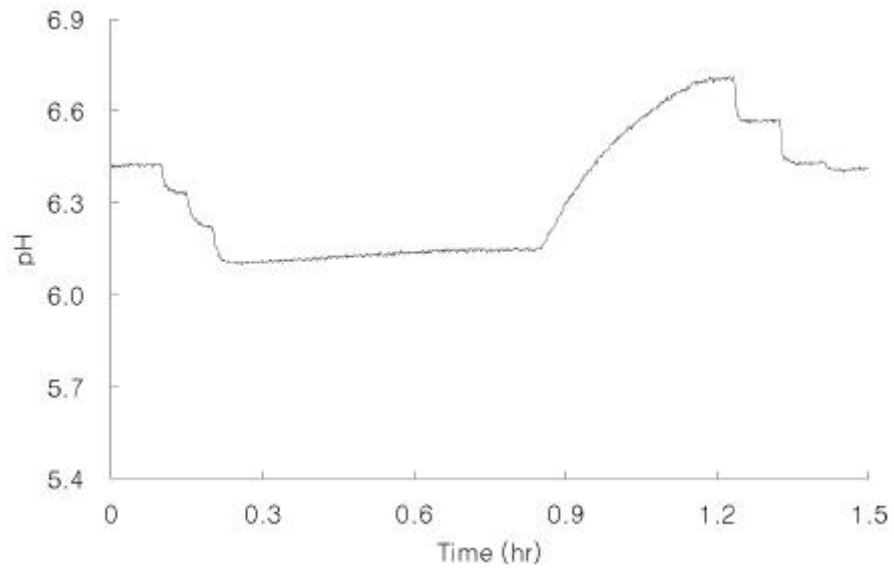
가 22

6.0 pH

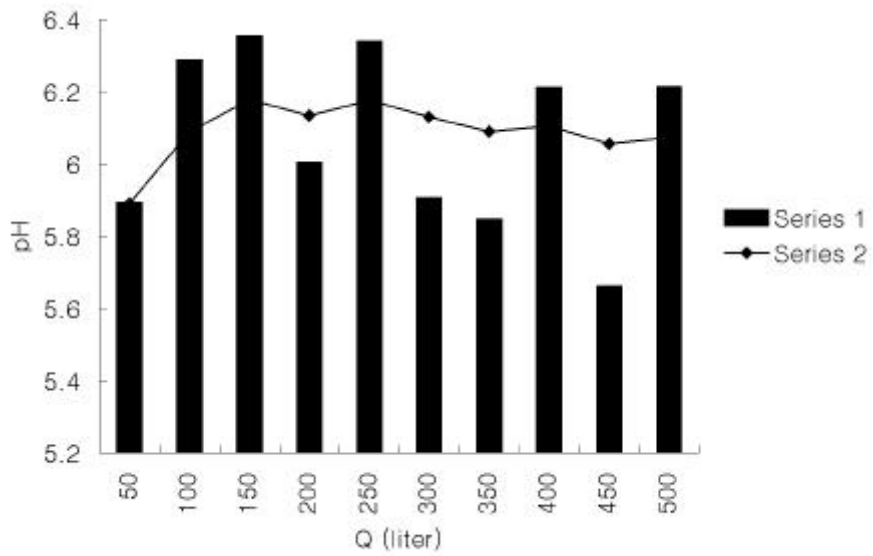
500

6.1 pH

가 가 .

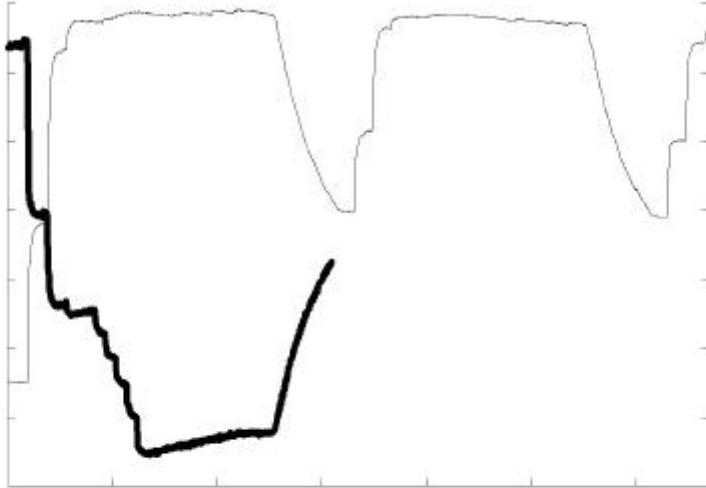


< 4-10>



< 4-11> NETAFIM

< 4-12>



< 4-12>

4.3.4.

2

< 4-2>

가 2.4 %

± 0.05 mS/cm

< 4-2> 2

Date	10/21	10/28	11/4	11/11	11/18	11/25
EC (mS/cm)	1.385	1.401	1.366	1.391	1.421	1.391
Error (%)	1.4	0.07	2.4	0.6	1.5	0.6

, , / ,

< 4-3> . 11 1 12 15 5
 9 < 4-4> .
 < 4-5> < 4-6> Ca Mg
 . Ca Mg 0.5 %, 1.8 %
 0.48 %

< 4-3>

Date	Leaf position	Leaf length, (L) (mm)	Leaf width, (W) (mm)	L/W	Stem diameter (mm)
10/21	3	54.5	48.2	1.13	16.77
	4	51.9	46.1	1.13	
10/28	3	55.6	50.1	1.11	17.33
	4	52.5	46.3	1.13	
11/4	3	56.2	50.7	1.11	17.73
	4	53.2	47.5	1.12	
11/11	3	56.6	60.0	1.13	17.83
	4	53.5	47.7	1.12	
11/18	3	56.8	51.1	1.11	17.90
	4	53.7	48.2	1.11	
11/25	3	57.0	51.8	1.10	17.91
	4	54.0	48.5	1.11	

< 4-4>

Period	11/1	11/6	11/11	11/16	11/21	11/26	12/1	12/6	12/11
	11/5	11/10	11/15	11/20	11/25	11/30	12/5	12/10	12/15
Yield (kg/day)	0.53	0.73	1.04	1.14	3.06	3.44	3.70	3.96	4.70

< 4-5>

Ca

Replication No.	1	2	3
Mass (mg/)	162.5	163.8	162.7
Deviation (%)	0.3	0.5	0.2

< 4-6>

Mg

Replication No.	1	2	3
Mass (mg/)	50.3	52.0	51.5
Deviation (%)	1.8	1.4	0.5

4. 4.

가 가

100

가

PC

PC

가

5.

5. 1.

Benoit(1992)

가

가

가

(1995)

EC pH

가

1996).

(1995)

1.1mS/cm

1.7mS/cm

1

EC

2.3mS/cm

30%

EC, pH

가

Taikichi(1988)

EC

1mS/cm

2mS/cm

EC

가

山崎(1984)

(1997)

EC, pH

가

1 10 15

1 8 10

1

1 1 2

1 1

1 2

Gieling(1988)

EC

가

가

가

가

가

EC

5. 2.

5.2.1.

가

40kLux 70kLux

70kLux

5.2.5.

20% 가

5.2.6. pH

pH

pH

, CO₂ ,

Schwarz(1995)

가

pH

5.5 6.5 가

5.2.7.

EC

2.5mS/cm

, 1.8 2.0mS/cm,

1.7mS/cm

. 1.5 2.0mS/cm ,

1.5

2.0mS/cm, 2.0 3.0mS/cm .

5. 3.

5.3.1.

가

가

가

, 16

2

A/D

4 20mA 2

5.3.2.

, (),

5. 3. 2. 1.

가 . , ,
가 , , (經時的)
(時定數)가 가
가
가
(Pt- 100) 가 가

가
 , 가 ,
 2 3
 가
 4 . 4
 2

KH-2110
 0.1 ±0.1
 4 20 mA (< 5-1>).

< 5-1>

Specifications	Temperature
Manufacturer	KONICS Co.
Range	- 200 600
Resolution	0.1
Accuracy	±0.1
Sensing type	Resistance detector
Output	4 20 mA

5.3.2.2.

가

가

HANNA HI943500

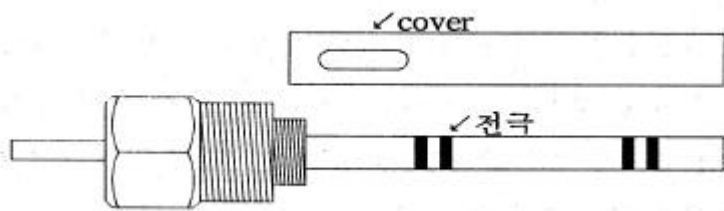
< 5-2>). 0 19.99 mS/cm

0.01 mS/cm, ± 2 % F.S. 4 20 mA

< 5-2>

Specifications	EC
Manufacturer	HANNA Inst.
Range	0 19.99 mS/cm
Resolution	0.02 mS/cm
Accuracy	± 2% FS
Sensing type	Impedance type
Output	4 20 mA

< 5-1>



< 5-1>

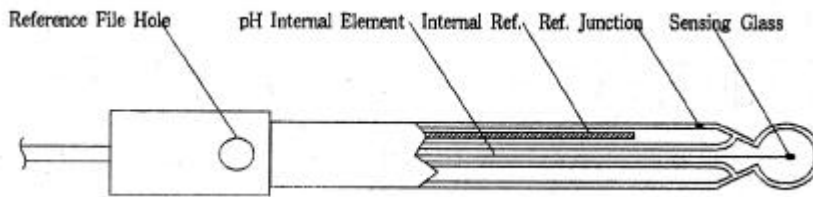
5. 3. 2. 3.

pH

(reference electrode)

(glass electrode)

< 5-2>



< 5-2>

HANNA HI8710 0
 14 pH 가 0.01 pH, ±0.02 pH 4
 20 mA (< 5-3>).

< 5-3>

Specifications	pH
Manufacturer	HANNA Inst.
Range	0 14 pH
Resolution	0.01 pH
Accuracy	±0.02 pH
Sensing type	Combination electrode type
Output	4 20 mA

5.3.2.4.

1

(level)

(< 5-4>).

< 5-4>

		(float),

5.3.3.

5.3.3.1.

5.3.3.1.1.

(光電) (Photoconductive) , (Photovoltaic)
, (Photoemissive) ,

5.3.3.1.2.

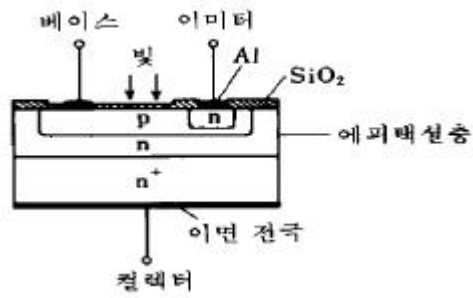
가 , 가
NPN (epitaxial) P
(emitter), (collector) 가
, (IE)
가
가 ,
< 5-4>

< 5-5> , 4 20mA

CRN-96R

<

5- 6>



< 5- 4>

< 5- 5>

Type	Photovoltaic detector
Range	280 2,800 nm
Temperature	- 15 +50
Wire Length	15m

< 5- 6>

Output	Ampere	4 20mA DC
	Solar Energy	0 1500 W/m2
Dimension		96(W) × 96(H) × 146(D)
Source		AC 110/220V

5. 3. 3. 2. -

PT 100 RTD

Pt- 100

(g/m³),
(kg/kg'),
(% RH) , 露
點 .
 ,
 , , .
가

5. 4.

가

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가

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, 가

,

가

가

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5.4.1.

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, , ,

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가

.

5. 4. 1. 1.

가 ,

가 .

FAX , .

가

가 가 .

가

가 , 가

가 “ ”_“

”_“ ” 가 “ ”_“ ”_“

”_“ ”

가 가 , crisp

가 가 . ,

“ 가 ” 30

25 “ ” .

IF- THEN production rule

가

가

.

5.4.1.2. .

, , , ,

. < 5-7> .

(label) , < 5-6> < 5-8>

, , ,

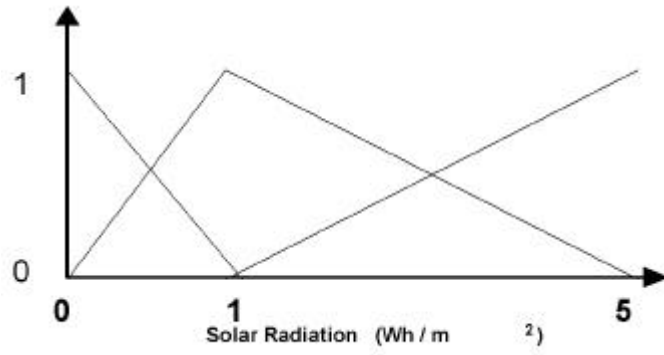
.

< 5-9> < 5-10>

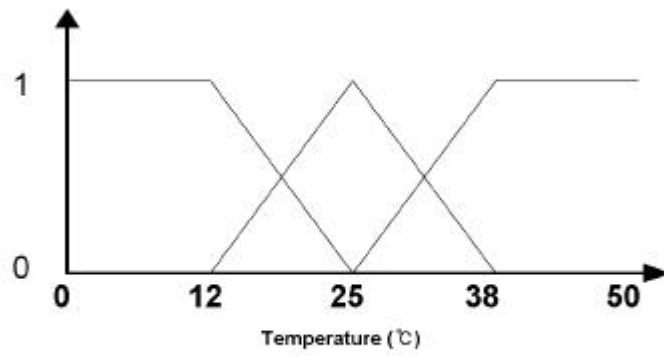
.

< 5-7>

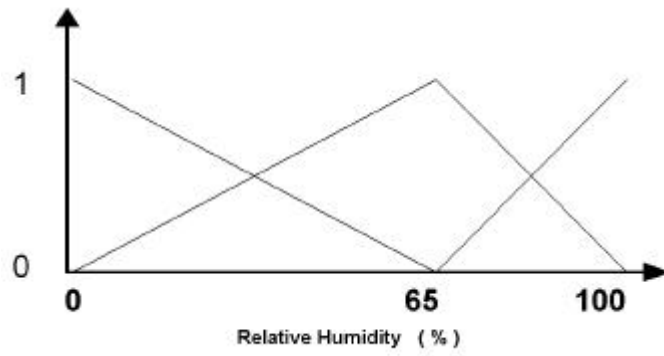
			Low Medium High
			Low Medium High
			Low Medium High
			Seed Culture Harvest
		EC	VLow Low Medium High VHigh
			Low Medium High



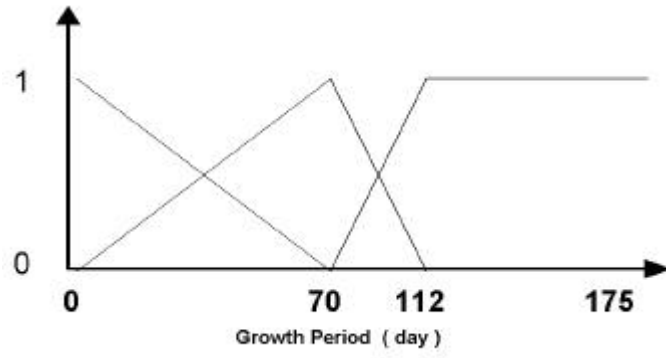
< 5-5 >



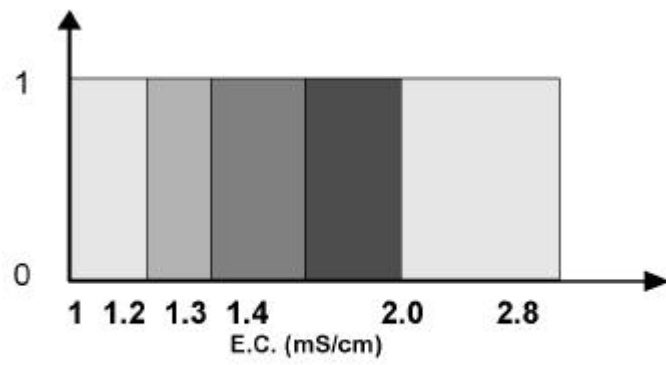
< 5-6 >



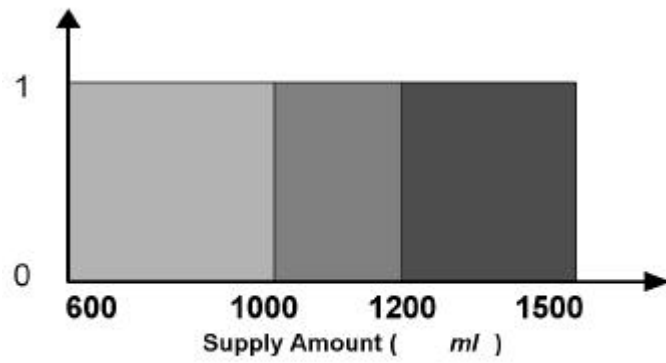
< 5-7 >



< 5-8 >



< 5-9 >



< 5-10 >

5.4.1.3.

[IF (前提, antecedent) THEN
(結果, consequent)] production rule .
3 , 4 ,
2 9 .
9 production form < 5-8>

1. IF ["High"] THEN [Supply- amount "High"]
2. IF ["High"] THEN [EC "VLow"
& Supply- amount "High"]
3. IF ["Low"] THEN [Supply- amount "High"]
4. IF ["Medium"] THEN [Supply- amount "Medium"]
5. IF ["High"] THEN [Supply- amount "Low"]
6. IF ["Medium"] THEN [EC "Medium"
& Supply- amount "Medium"]
7. IF ["Seed"] THEN [EC "Medium"]
8. IF ["Culture"] THEN [EC "VHigh"]
9. IF ["Harvest"] THEN [EC "High"]

< 5-8 >

	Temperature			Solar Radiation			Relative Humidity			Growth Period			EC					Supply amount				
	L	M	H	L	M	H	L	M	H	S	C	H	VL	L	M	H	VH	L	M	H		
R 1.			■																		■	
R 2.						■								■								■
R 3.							■															■
R 4.								■													■	
R 5.									■												■	
R 6.	■														■						■	
R 7.										■					■							
R 8.											■						■					
R 9.												■				■						

5.4.2.

9

가

5.4.2.1.

9

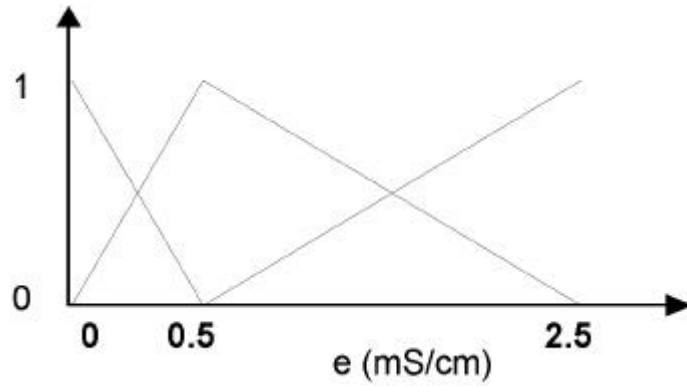
(trial and error)

5.4.2.2.

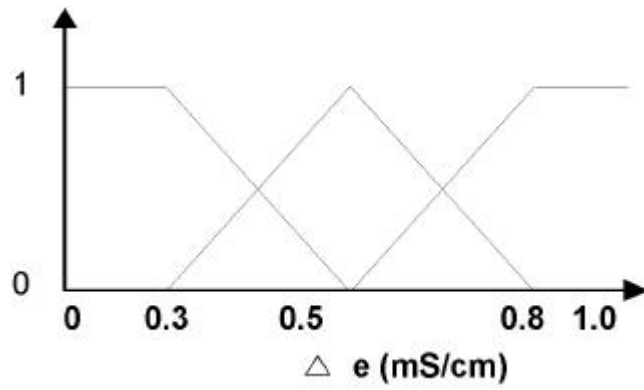
singleton

< 5-11> < 5-12>

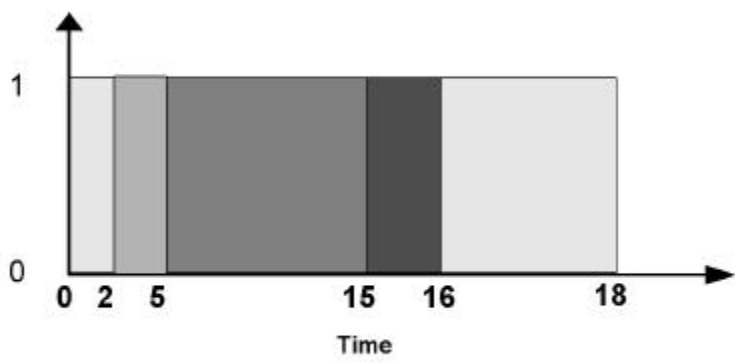
, < 5-13>



< 5-11>



< 5-12>



< 5-13>

5.4.2.3.

5-9> . 가 , 9 <
 가 가 ,
 가 .

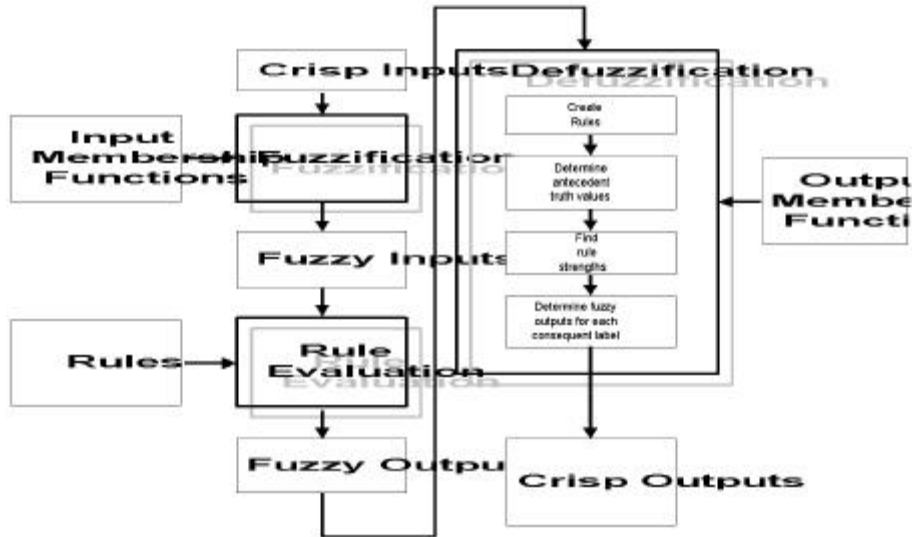
< 5-9>

	e			e			supply time				
	EL	EM	EH	EEL	EEM	EEH	t1	t2	t3	t4	t5
R 1.	■			■			■				
R 2.					■		■				
R 3.	■					■	■				
R 4.		■		■						■	
R 5.		■			■				■		
R 6.		■			■			■			
R 7.			■	■							■
R 8.			■		■					■	
R 9.			■			■				■	

5.4.3.

3

< 5- 14>



< 5- 14>

(fuzzy set)

(fuzzy distribution)

가

(defuzzification)

가

가

가

(center of

gravity, COG)

가 , 가

MOM(mean of maxima)

가 .

COG

COG

< 5-1>

$$\begin{aligned}
 x' &= \frac{\int_{x \in U} (x \cdot f(x)) dx}{\int_{x \in U} f(x) dx} \\
 &= \frac{\sum_{i=1}^n x'_i \cdot A_i}{\sum_{i=1}^n A_i}
 \end{aligned}
 \tag{5-1}$$

, x_i = recommended value

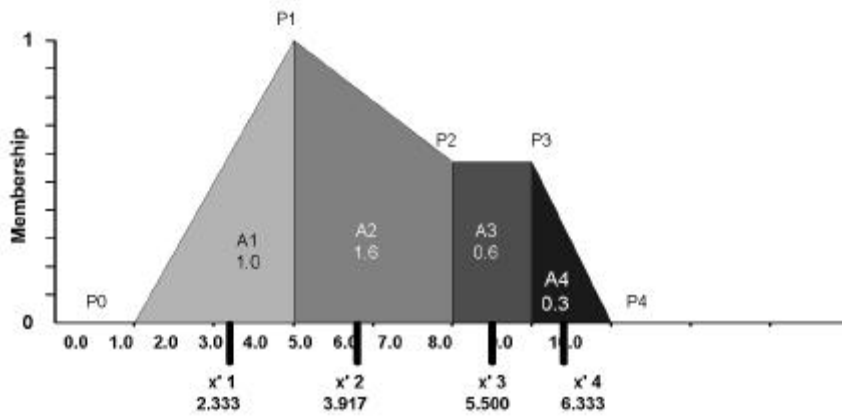
$$x'_i = [P_{i-1} \quad P_i] \tag{COG}$$

$$A_i = [P_{i-1} \quad P_i]$$

U = universe of discourse

n =

< 5-15> COG



< 5-15> COG

4

A1 A4

1.0, 1.6, 0.6, 0.3

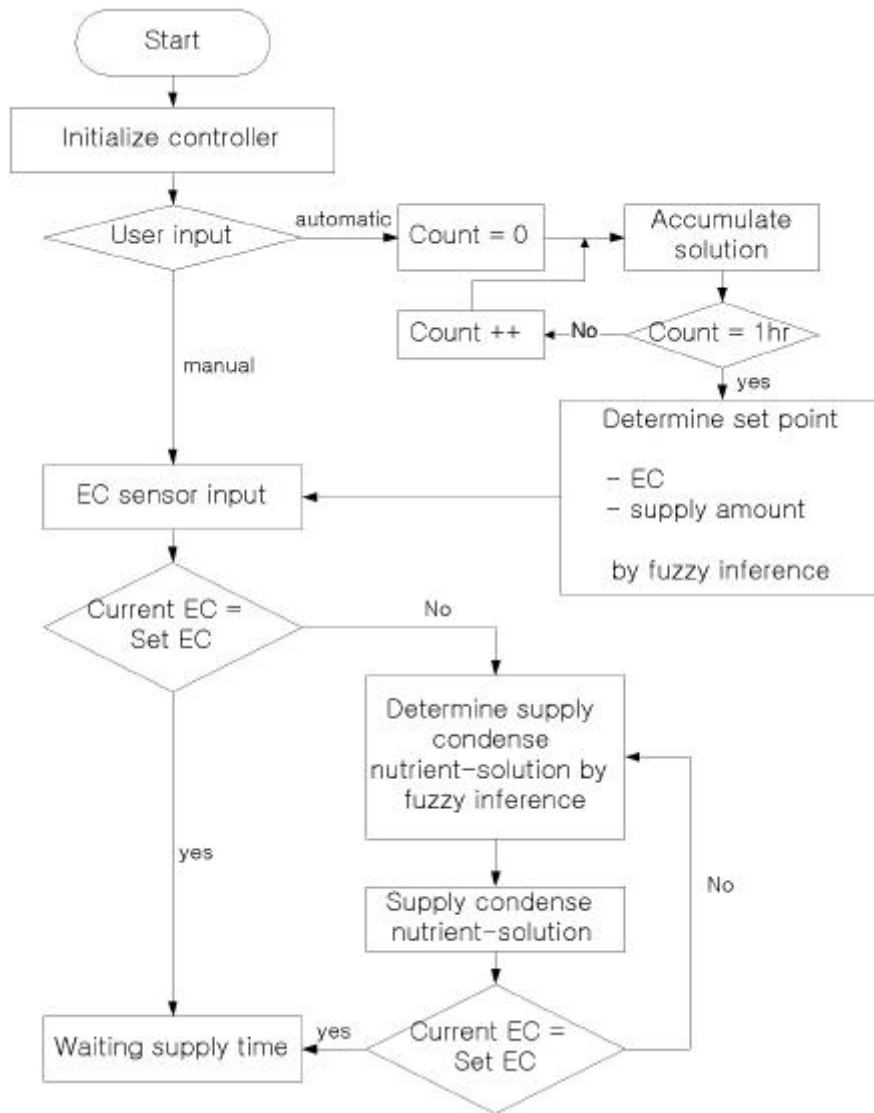
< 5-2>

$$x' = \frac{2.333 \times 1.0 + 3.917 \times 1.6 + 5.5 \times 0.6 + 6.333 \times 0.3}{1.0 + 1.6 + 0.6 + 0.3} \quad < 5-2>$$

$$= 3.943$$

5.4.4.

< 5-16 >



< 5-16 >

5. 5.

5.5.1.

5. 5. 1. 1.

가 PC

가

5. 5. 1. 2.

Embedded Controller, Keymatrix, ADC , LCD, Sensor transmitter

(Embedded controller)

Single Board

PC 486, Pentium 8bit CPU

, 32bit CPU 가

가 ,

A/S, , Application 가

V40, V25 CPU IBM- PC
100%

PC86- single board PC

< 5- 10>

< 5- 10>

Manufacturer	TURSystem (KOREA)
CPU	F8680A- 3MIPS (Chips&Technology, USA)
Operating System	ROM- DOS 6.22
Graphic	CGA Graphic Controller
COM	RS- 232, RS- 422, RS- 485
RAM	640 Main Memory
Keyboard Interface	Standard XT keyboard Interface + 64key matrix
SIZE	189(H) × 120(V)

8 × 8 keymatrix XT keyboard QWERTY

A Z 26 alphabet key F1 F8 8 function key,
, , , 4 direction key, 0 9 10 numeric key
enter, back space, space bar, shift control key

keymatrix

ROM- DOS

< 5- 17> keymatrix

COL	①	②	③	④	⑤	⑥	⑦	⑧	
ROW	①	A	B	C	D	E	(Shift)	-	F1
	②	F	G	H	I	J	K	L	F2
	③	K	L	M	N	O	(Back Space)	P	F3
	④	P	Q	R	S	T	U	V	F4
	⑤	U	V	W	X	Y	Z	[]	F5
	⑥	[]	[]	[]	[]	[]	(Enter)	[]	F6
	⑦	[]	[]	[]	[]	[]	(Space Bar)	[]	F7
	⑧	[]	[]	[]	[]	[]	[]	[]	F8

< 5- 17> 8 × 8 keymatrix

AD

pH 2 가 6 AD 가 1 DI , 8 DO 8 . AD
 < 5- 11>

< 5- 11> AD

Manufacturer		ADLink Technology Inc.,
Model		ACL8111
A/D	Type	successive approximation
	Resolution	12- bit
	Input Range	± 5V, ± 2.5V, ± 1.25V, ± 0.625V, ± 0.3125V
	Conversion Time	25 μ sec
	Accuracy	0.015% of reading ± 1 Bit LSB
DIO		16TTL compatible inputs & outputs

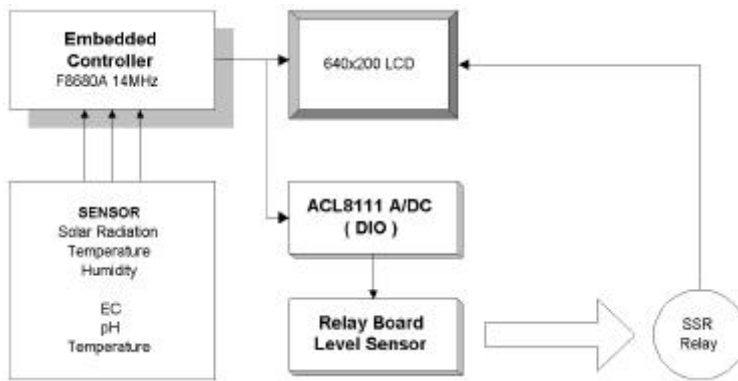
640 × 200 가 LCD

LCD 가

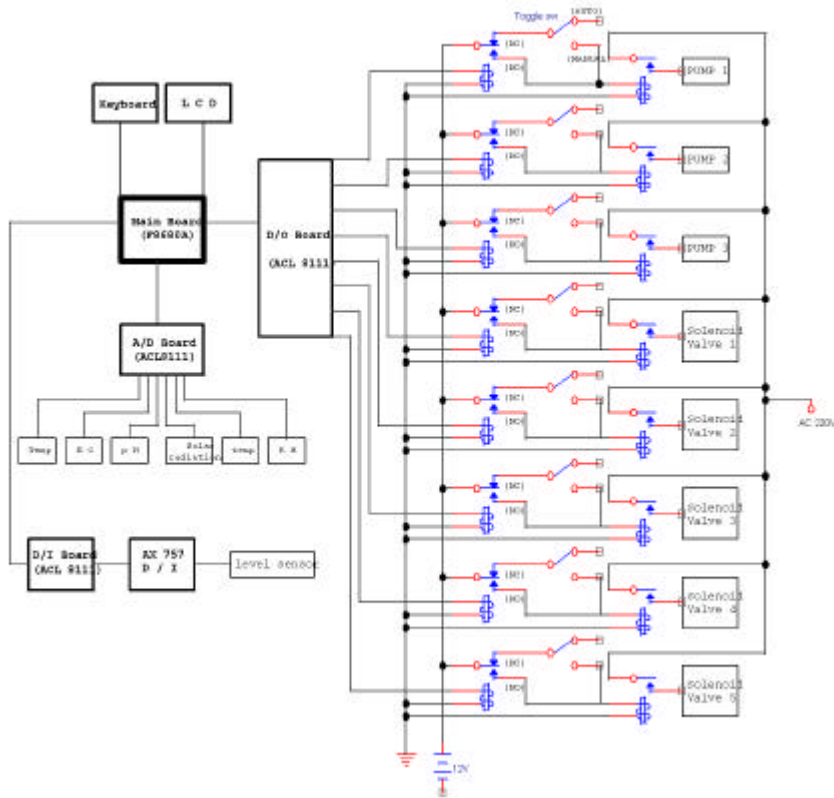
14pin CGA
monitor connector CPU PC86
AD PC86 ISA 4 BUS-Slot AD PC86
DATA, CONTROL, ADDRESSING 가

< 5- 18> F8680A, LCD, Sensor, ADC, Relay, SSR

< 5- 19>



< 5-18 >



< 5-19 >

5.5.2.

5.5.2.1.

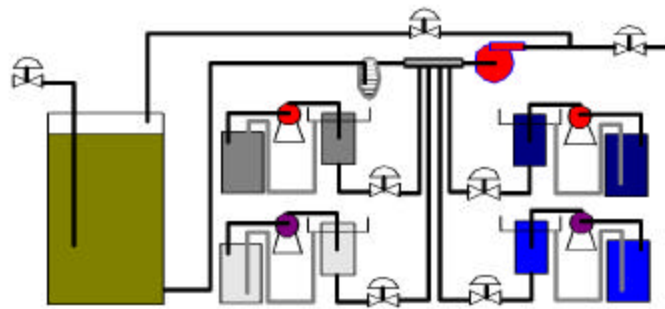
A, B

. <

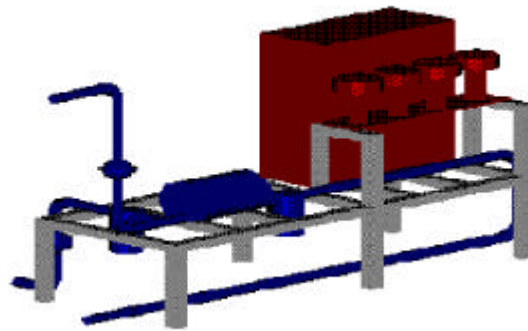
5-20>

, , ,

< 5-21>



< 5-20>



< 5-21>

5. 5. 2. 2.

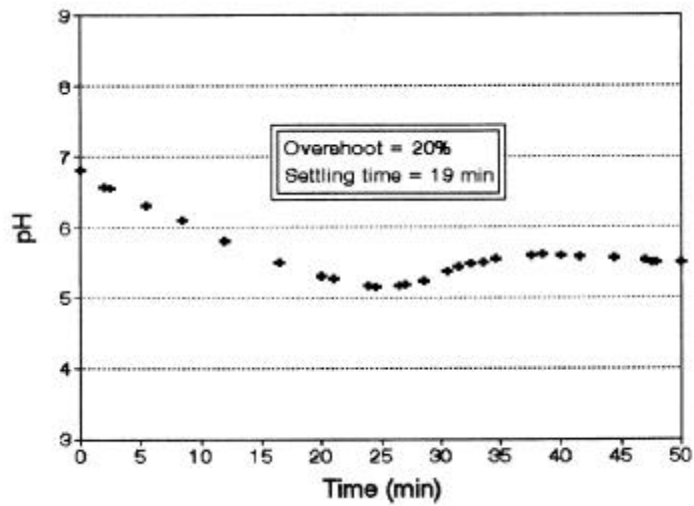
PVC

가

가

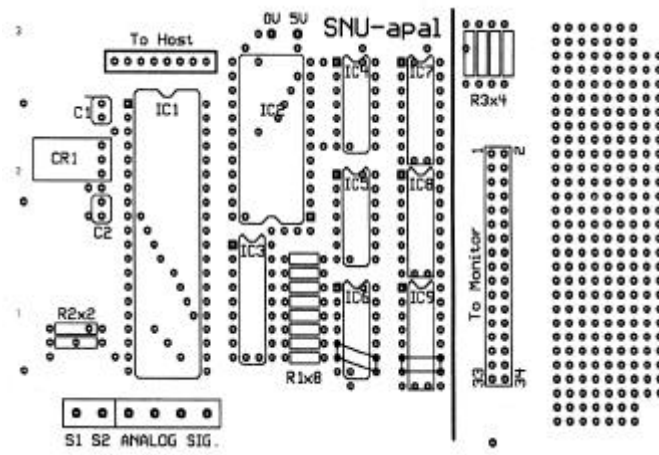
가

, < 5-22>



< 5-22>

< 5-23>

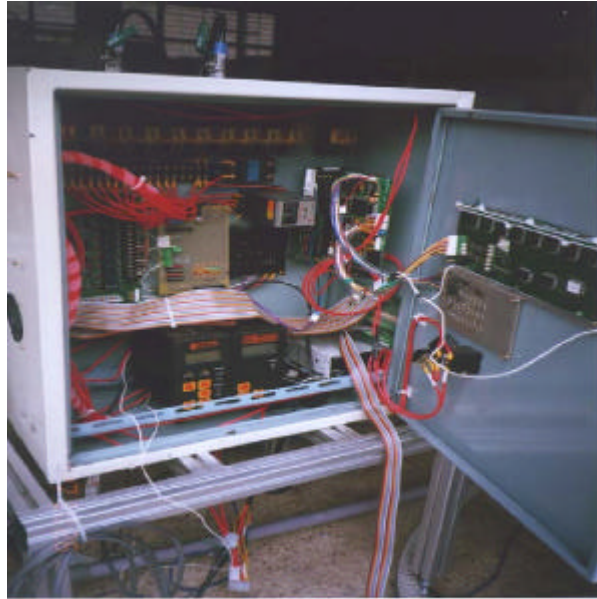


< 5-23>

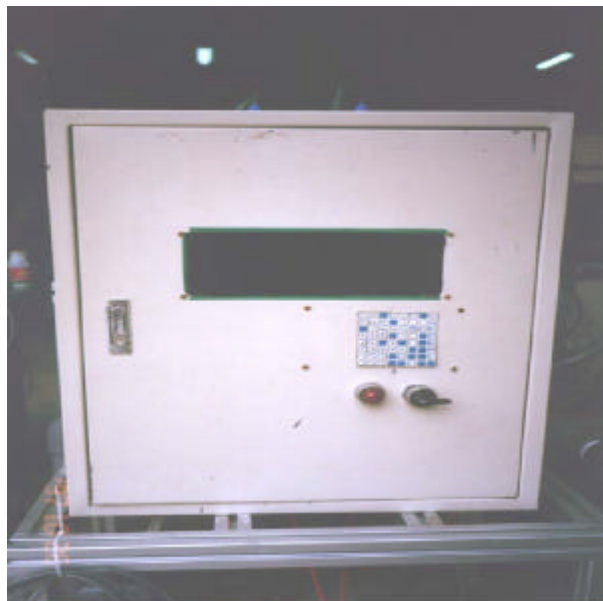
5.5.2.3.

keymatrix LCD 가
 가 ,
 가 .

< 5-24>, < 5-25>



< 5-24 >



< 5-25 >

5. 5. 2. 4.

가

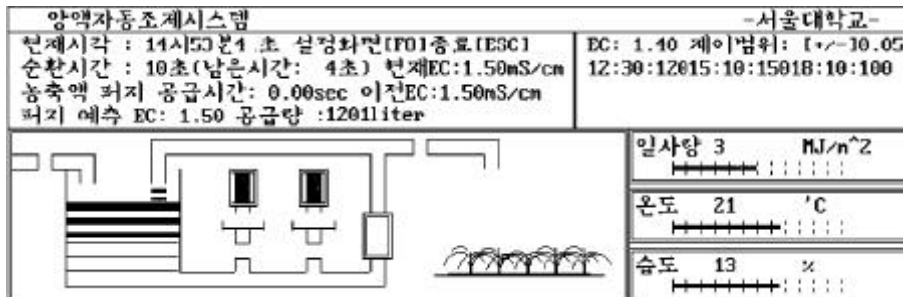
, B , A , B , ON- OFF

가

< 5- 26>, < 5- 27> 640 × 200

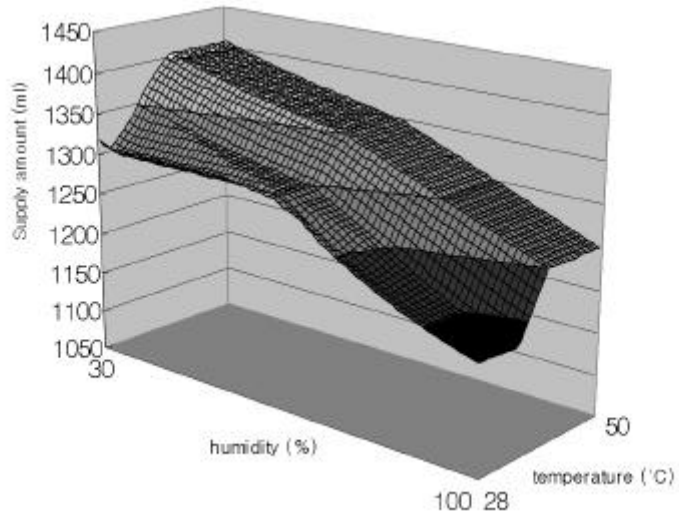
LCD

< 5- 26> , < 5- 27>



< 5- 26>

226M0



< 5-28 >

5. 5. 3. 1. 2.

가

< 5-29 > 2

2

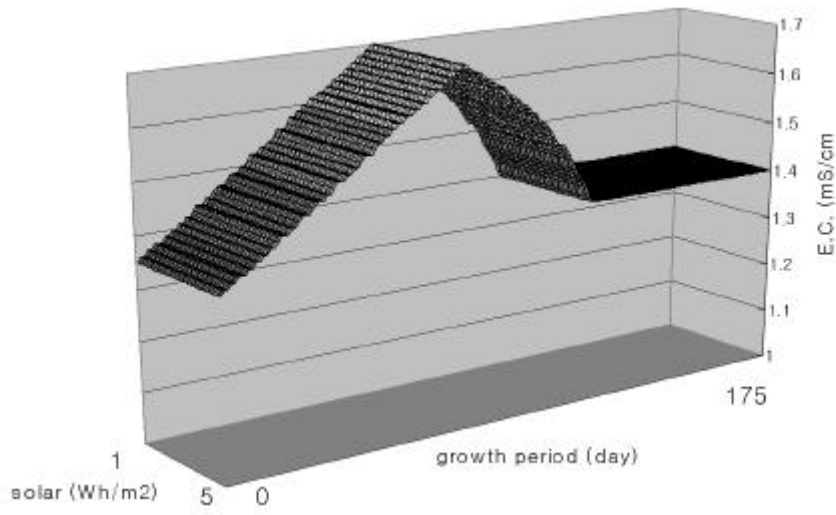
가

“ ”

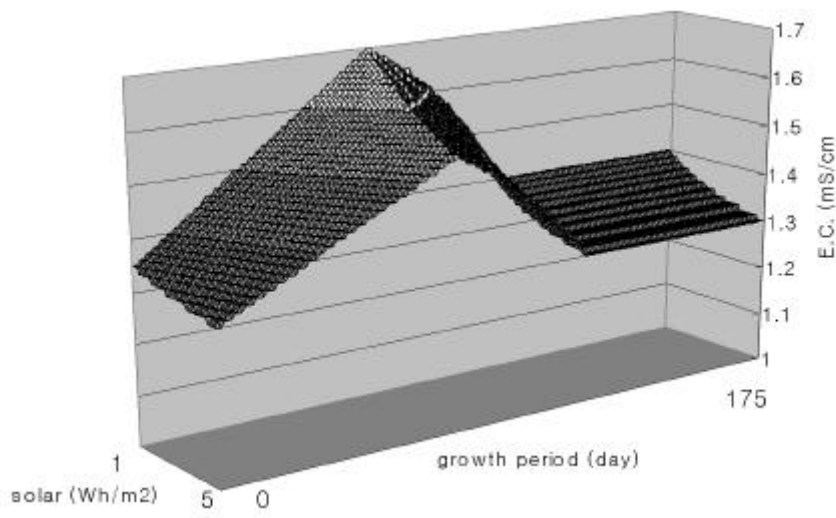
< 5-30 > 2

< 5-29 >

2 가



< 5-29 >



< 5-30 >

가

5. 5. 3. 2.

0.7 mS/cm

가

가

가

가 0.1mS/cm

5 , 0.2 mS/cm

10 , 0.3 mS/cm

0.7 mS/cm

15 , 1.0 mS/cm

20 , 1.3 mS/cm

25

< 5-31>

(1.0 mS/cm)

(0.3 mS/cm)

가

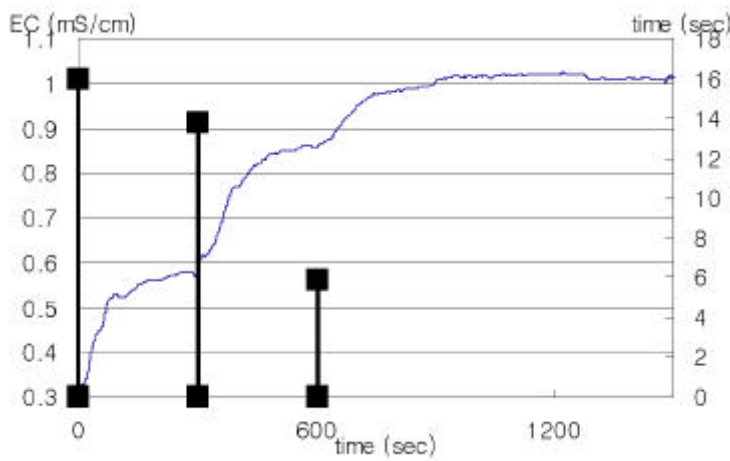
0.7 mS/cm

15

0.015

mS/cm

3

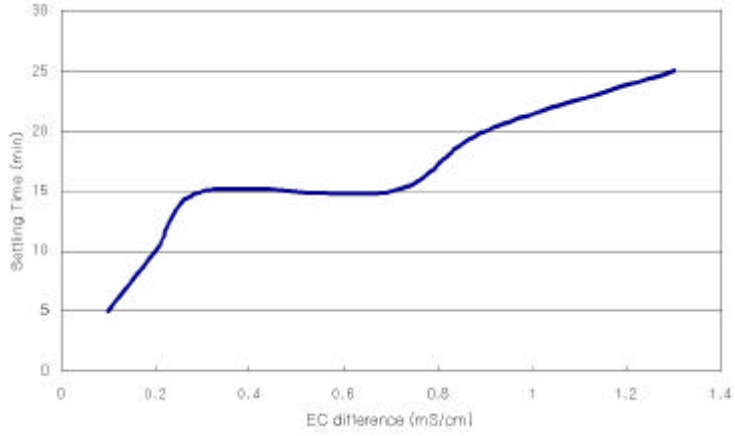


< 5-31>

가 0.7mS/cm

< 5-32>

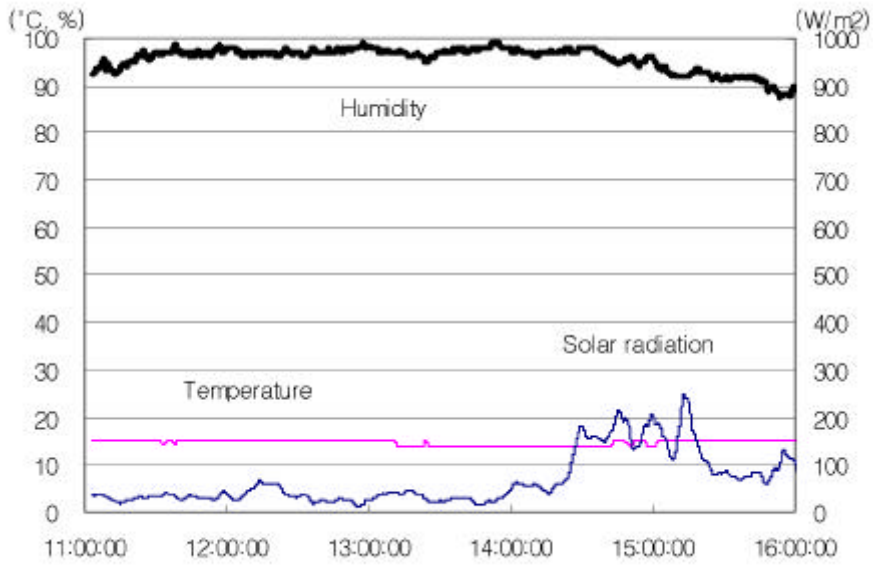
, 가 0.1mS/cm 0.7mS/cm
15 , 0.035mS/cm .



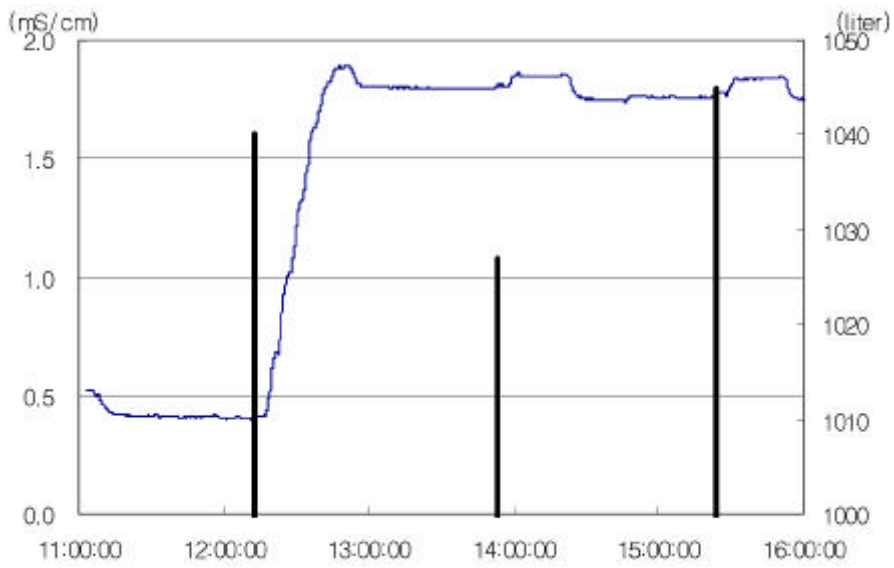
< 5-32>

가 < 5-33>

< 5-34> . < 5-34>



< 5-33> , ,



< 5-34> 3 ,

5. 6.

3가

,

가 ,
가

가 ,

가 가

6.

- 가
- 가
1. 가
- ± 0.06 , $\pm 0.03\text{mS/cm}$, $\pm 0.08\text{pH}$
- 가
2. 가

가 , 가

가

3.

9.11% , 8.46%

가

(R2) 0.9999

0.48%

가

(R2)

0.9999

0.2%

4.

2

4 ± 1

± 0.05 mS/cm,

± 0.2pH

15

22 ± 1

1.4mS/cm

500

1.29mS/cm,

6.0pH

500

6.1pH

± 0.05mS/cm

5.

가
0.035mS/cm 15

가 가 가

가.
○
○
가
○ 가 가
○ 가

○

가 가

○

○

○

○

○

가

가.

가

가.

가

가

가 가

1 2

가

가 가

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